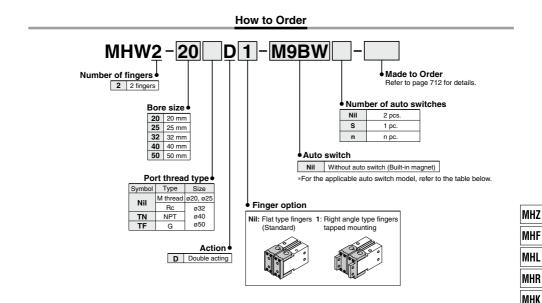
180° Angular Type Air Gripper Rack & Pinion Type MHW2 Series ø20, ø25, ø32, ø40, ø50



Applicable Auto Switches / Refer to pages 797 to 850 for further information on auto switches

		-			Load voltage				Load voltag		L oad voltago		Loadyr		Load voltage		enetlov beo l		Load voltago		ch model	Ŀ	ead wire I	ength (m)	1*			
Туре	Special function	Electrical entry	Indicator light	Wiring (Output)			-	Electrical en	try direction	0.5	1	3	5	Pre-wired connector		cable												
	Turicuon	Chury	light	(Output)		DC	AC	Perpendicular	In-line	(Nil)	(M)	(L)	(Z)	connector	10	load												
				3-wire(NPN)		5 V. 12 V		M9NV	M9N	۲	•	•	0	0	IC													
5 C				3-wire(PNP)]	5 V, 12 V		M9PV	M9P	۲	•	•	0	0	circuit													
switch				2-wire	- I5V 12VI	12 V	12 V	M9BV	M9B	•	•	•	0	0	_													
auto :	Diagnosis			3-wire(NPN)		4 15		M9NWV	M9NW	۲	•	•	0	0	IC													
		Grommet	Yes	3-wire(PNP)			-	M9PWV	M9PW	۲	•	•	0	0	circuit	Relay, PLC												
state	indicator)			2-wire]	12 V		M9BWV	M9BW	•	•	•	0	0	_													
Solid :	Water			3-wire(NPN)]	EV 10 V		M9NAV**	M9NA**	0	0	•	0	0	IC													
So	resistant (2-color			3-wire(PNP)) 5	5 V, 12 V		M9PAV**	M9PA**	0	0	•	0	0	circuit													
	indicator)			2-wire]	12 V		M9BAV**	M9BA**	0	0	•	0	0	_													

** Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance. * Lead wire length symbols: 0.5 m Nil (Example) M9NW * Auto switches marked with a "O" symbol are produced upon receipt of order.

- 1 m ······· M (Example) M9NWM

 - 3 m ······· L (Example) M9NWL 5 m ······ Z (Example) M9NWZ

Note 1) When using the 2-color indicator type, please make the setting so that the indicator is lit in red to ensure the detection at the proper position of the air gripper.

Note 2) When ordering the air gripper with the auto switch, the auto switch mounting bracket is included.

When ordering the auto switch separately, the auto switch mounting bracket (BMG2-012) is required.

@SMC

MHS

MHC МНТ MHY MHW -X□ MRHO

MA

D-🗆



Specifications

Fluid	Air
Operating pressure	0.15 to 0.7 MPa
Ambient and fluid temperature	-10 to 60°C
Repeatability	±0.2 mm
Max. operating frequency	ø20, 25: 60 c.p.m.
	ø32 to 50: 30 c.p.m.
Lubrication	Not required
Action	Double acting
Auto switch (Option) Note)	Solid state auto switch (3-wire, 2-wire)

Note) Refer to pages 797 to 850 for further information on auto switches.

Symbol

Double acting: External grip



Made to Order	Made to Order Click here for details
Symbol	Specifications/Description
-X4	Heat resistance
-X5	Fluororubber seal
-X50	Without magnet
-X53	EPDM for seals, Fluorine grease
-X63	Fluorine grease

Grease for food processing machines, Fluorine grease

Grease for food processing machines

Model

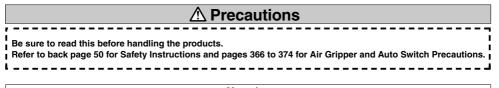
Model	Bore size (mm)	Effective gripping force (N·m)	Openin (Both Opening	sides)	Weight ⁽²⁾ (g)
MHW2-20D	00	0.30		-5°	300
MHW2-20D1	20	0.30		-5	320
MHW2-25D	25	0.73	180°	-6°	510
MHW2-25D1	25	0.73			540
MHW2-32D	00	1.61			910
MHW2-32D1	32				950
MHW2-40D	40	3.70]	–5°	2140
MHW2-40D1	40	3.70			2270
MHW2-50D	50	8.27		-4°	5100
MHW2-50D1	50	0.27		-4	5350

Note 1) At the pressure of 0.5 MPa

Note 2) Except auto switch

Refer to "How to Select the Applicable Model" on page 700

 Refer to pages 700 and 701 for the details on effective holding force and allowable overhanging distance.



Mounting

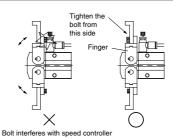
MHW

-X79

-X79A

A Warning

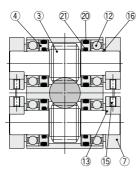
When using right angle finger tap mounting type, monitor the interference of the bolt with the speed controller.

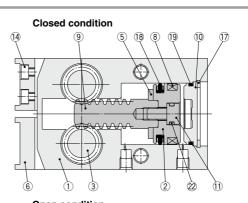


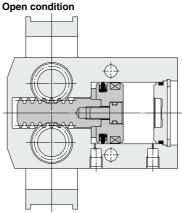
A 712



Construction







Component Parts

No.	Description	Material	Note
1	Body	Aluminum alloy	Hard anodized
2	Piston	Aluminum alloy	Hard anodized
3	Pinion gear	Carbon steel	Heat treated
4	Seal cover	Brass	
5	Bumper	Urethane rubber	
6	Finger (A)	Carbon steel	Nitriding
7	Finger (B)	Carbon steel	Nitriding
8	Rubber magnet	Synthetic rubber	
9	Rack	Carbon steel	Nitriding

No.	Description	Material	Note
10	Сар	ø20, 25: Resin	
10	•	ø32 to 50: Aluminum alloy	Hard anodized
11	Piston bolt	Stainless steel	
12	Ball bearing	Carbon steel	Schield type
13	Key	Carbon steel	
14	Hexagon socket head bolt	Carbon steel	Zinc chromated
15	Hexagon socket cap screw	Carbon steel	Zinc chromated
16	Type C retaining ring	Carbon steel	Phosphate coated
17	Type C retaining ring	Carbon steel	Phosphate coated

Replacement Parts

Description		MHW2-20	MHW2-25	MHW2-32	MHW2-40	MHW2-50	Main parts
Seal kit		MHW20-PS	MHW25-PS	MHW32-PS	MHW40-PS	MHW50-PS	1819202122
Piston assembly		MHW-A2001	MHW-A2501	MHW-A3201	MHW-A4001	MHW-A5001	25891122
Finger assembly	MHW2-□D	MHW-A2002	MHW-A2502	MHW-A3202	MHW-A4002	MHW-A5002	67131415
Finger assembly	MHW2-DD1	MHW-A2002-1	MHW-A2502-1	MHW-A3202-1	MHW-A4002-1	MHW-A5002-1	
Finger A assembly	MHW2-□D	MHW-A2006	MHW-A2506	MHW-A3206	MHW-A4006	MHW-A5006	614
Finger C assembly MHW2-DD1		MHW-A2006-1	MHW-A2506-1	MHW-A3206-1	MHW-A4006-1	MHW-A5006-1	614
Finger B assembly		MHW-A2007	MHW-A2507	MHW-A3207	MHW-A4007	MHW-A5007	71315

* Please order 1 piece finger assembly per one unit.

Replacement part/grease pack part no. : ø20, ø25, ø32 : GR-S-010(10 g)

ø40, 50 : GR-S-020(20 g)

MHZ MHF MHL

MHR

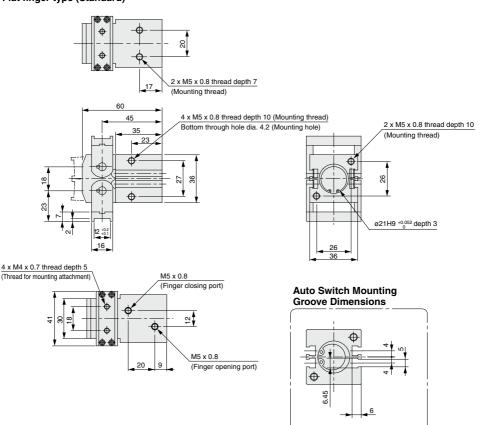
MHK MHS MHC

MHT MHY MHW -X🗆 MRHQ MA

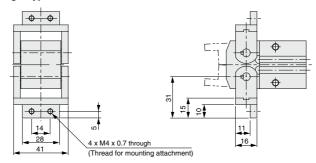
D-🗆

Dimensions

MHW2-20D Flat finger type (Standard)



MHW2-20D1 Right angle finger type



Dimensions

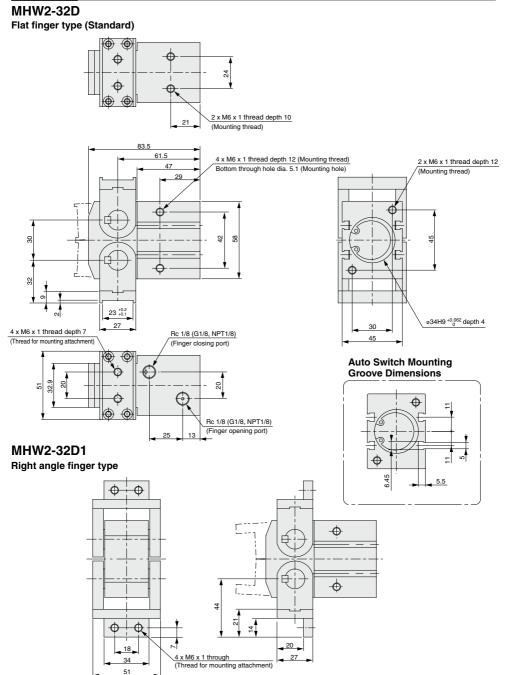
MHW2-25D Flat finger type (Standard) ⊕⊕ Ð 24 Ð ۲ 6 2 x M6 x 1 thread depth 10 20 (Mounting thread) 4 x M6 x 1 thread depth 12 (Mounting thread) 69 2 x M6 x 1 thread depth 12 51 Bottom through hole dia. 5.1 (Mounting hole) (Mounting thread) 40 2 55 24 34 8 Œ 27 17 +0.1 ø26H9 +0.052 depth 3 MHZ 30 21 40 MHF 4 x M5 x 0.8 thread depth 6 M5 x 0.8 (Thread for mounting attachment) (Finger closing port) Auto Switch Mounting Groove Dimensions MHL 1 MHR \$ 16 S MHK Ð ⊕€ MHS 23 10 M5 x 0.8 (Finger opening port) MHC 4.5 MHT MHW2-25D1 6.45 5.5 Right angle finger type MHY MHW φ Φ -X🗆 MRHQ Φ MA D-🗆 \oplus 37 ¢ æ <u>م</u> ŝ 16 15 4 x M5 x 0.8 through 30 21



(Thread for mounting attachment)

45

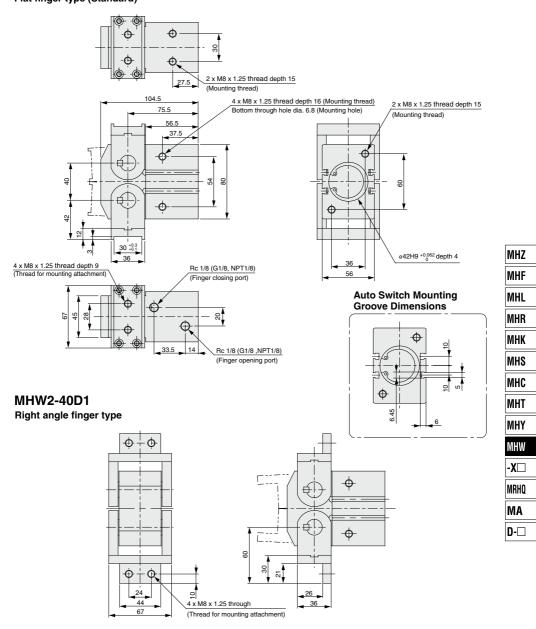
Dimensions



SMC

Dimensions

MHW2-40D Flat finger type (Standard)

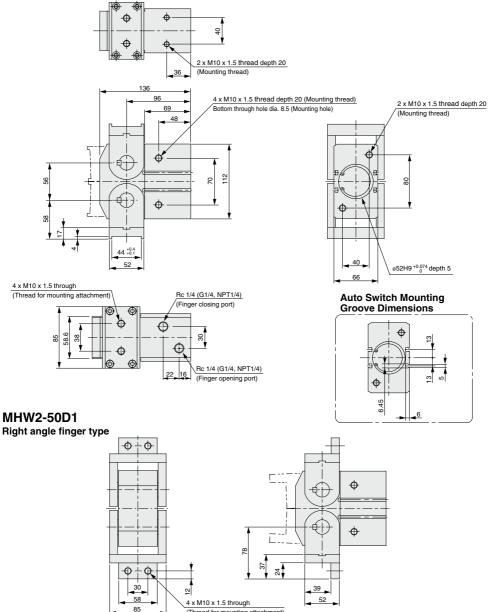




Dimensions

MHW2-50D

Flat finger type (Standard)



(Thread for mounting attachment)



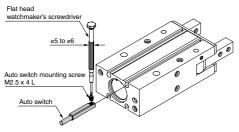
MHY2/MHW2 Series **Auto Switch Installation Examples** and Mounting Positions

Various auto switch applications are possible through different combinations of auto switch quantities and detecting positions. **Detection when Gripping Exterior of Workpiece**

Detection example	1. Confirmation of the fingers in reset position	2. Confirmation of work held		
Position to be detected	Position of fingers fully opened	Position when gripping a workpiece		
Operation of auto switch	Auto Switch turned ON when fingers return. (Light ON)	Auto Switch turned ON when gripping a workpiece. (Light ON)		
How to determine auto switch installation position	Step 1) Completely open the fingers.	Step 1) Position fingers for gripping a workpiece.	MHZ	
At no pressure or low pressure, connect the auto switch to a	Step 2) Insert the auto switch into the switch groove in the direction shown in the drawing.	Step 2) Insert the auto switch into the switch groove in the direction shown in the drawing.	MHF	
power supply, and follow the directions.				
	Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates.	Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates. Move the switch an additional 0.3 to 0.5 mm in the direction of the arrow and fasten it.	MHS MHC	
	Step 4) Slide the auto switch further in the direction of	Position where light turns ON	MHT	
	the arrow until the indicator light goes out.		MHW	
	Step 5) Move the auto switch in the opposite direction	Position to be secured	-X□ Mrhq	
	and fasten it at a position 0.3 to 0.5 mm beyond the position where the indicator light illuminates.		MA	
	Position where light turns ON Position to be secured		D -□	

Auto Switch Mounting

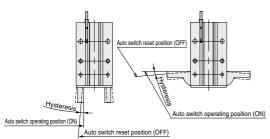
To set the auto switch, insert the auto switch into the installation groove of the gripper from the direction indicated in the following drawing. After setting the position, tighten the attached auto switch mounting set screw with a flat head watchmaker's screwdriver.



- Note) Use a watchmaker's screwdriver with a grip diameter of 5 to 6 mm to tighten the auto switch mounting screw. Also, tighten with a torque of about 0.05 to 0.15 N·m, or about 0.05
 - to 0.10 N·m for D-M9 \square A(V).
- * Refer to the page 804 for the details on "Auto Switches Connection and Example".

Auto Switch Hysteresis

Auto switches have hysteresis similar to micro switches. Use the table below as a guide when adjusting auto switch positions, etc.



		D-M9□(V) D-M9□W(V)/M9A(V)
MHY2	Finger fully closed	2°
-10D	Finger fully open	4 °
MHY2	Finger fully closed	2°
-16D	Finger fully open	3°
MHY2	Finger fully closed	2°
-20D	Finger fully open	3°
MHY2	Finger fully closed	1°
-25D	Finger fully open	2°

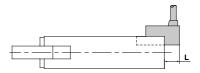
Protrusion of Auto Switch from Edge of Body

The projection of an auto switch from the edge of the body is shown in the table below. Use the table as a guideline for mounting.

Note) 2-color indicator type and perpendicular entry type protrude in the direction of the lead wire entry.



When auto switch D-M9 is used



When auto switch D-M9
V is used

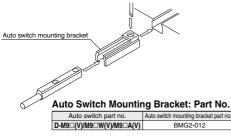
Max. Protrusion of Auto Switch from Edge of Body (L)

Auto	switch		Protrusion					
$ \setminus \frown$	model	In-line	Perpendicular	In-line	Perpendicular			
Air gripper model	nger isition	D-M9⊡ D-M9⊡W	D-M9⊡V D-M9⊡WV	D-M9⊡A	D-M9⊡AV			
MHY2-10D	Open	-	—	—	—			
WITT2-10D	Closed	3	1	5	3			
MHY2-16D	Open	-	-	—	-			
WIN 12-10D	Closed	3	1	5	3			
MHY2-20D	Open	_	_	_	_			
WITT 2-20D	Closed	—	—	3	1			
MHY2-25D	Open	_	_	_	_			
WIN 12-25D	Closed	—	—	1	—			

(mm)

Auto Switch Mounting

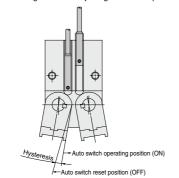
- (1) Insert the auto switch bracket into the installation groove of the gripper as shown below and roughly set it.
- (2) Insert the auto switch into the auto switch bracket installation groove.
- (3) After confirming the detecting position, tighten the set screws (M2.5) attached to the auto switch and set it.
- (4) Be sure to change the detecting position in the state of (2).



Note) Use a screwdriver with a grip diameter of 5 to 6 mm to tighten the set screws (M2.5). The tightening torque should be 0.5 to 1 N-m. As a rule, it should be turned about 90° beyond the point at which tightening can be felt.

Auto Switch Hysteresis

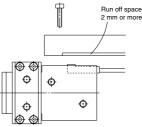
Auto switches have hysteresis similar to micro switches. Use the table below as a guide when adjusting auto switch positions, etc.



Auto switch Air gripper model model	D-Y59□/Y69□ D-Y7P(V)/Y7□W(V)
MHW2-20D	4°
MHW2-25D	4°
MHW2-32D	2°
MHW2-40D	2°
MHW2-50D	2°
Auto switch	Max. hysteresis (Max. value)
model	D-M9□(V)
Air gripper	D-M9□W(V)
model	D-M9□A(V)
MHW2-20D	4°
MHW2-25D	4°
MHW2-32D	2°
MHW2-40D	2°

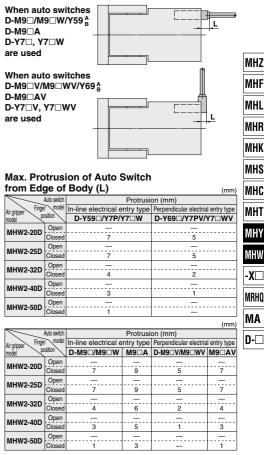
Handling of Mounting Brackets

When auto switch is set on mounting side as shown below, allow at least 2 mm run off space on mounting late since the auto switch is protruded from the gripper edge.



Protrusion of Auto Switch from Edge of Body

The maximum protrusion of an auto switch (when fingers are fully closed) from the edge of the body is shown in the table below. Use the table as a guideline for mounting.



MHF MHI MHR MHK MHS MHC MHT MHY MHW -X□ MRHO MA D-



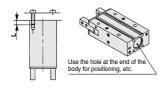
MHY2/MHW2 Series Specific Product Precautions 1

Be sure to read this before handling the products.

Mounting Air Grippers/MHY2 Series

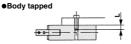
Possible to mount from 3 directions.

Axial Mounting (Body Tapped)



Model	Applicable bolts	Max. tightening torque (N·m)		Max. screw-in depth (Lmm)	
MHY2-10D	M3 x 0.5	0.88		6	
MHY2-16D	IHY2-16D M4 x 0.7 2		2.1	8	
MHY2-20D	M5 x 0.8	4.3		10	
MHY2-25D	M6 x 1	7	7.4	12	
Model Bore(mr		n)	Hole de	epth (mm)	
MHY2-10D	011119 (ø11H9 +0.043		1.5	
MHY2-16D	0.043 1.5		1.5		
MHV2-20D	a2140 +0	0.052	15		

Lateral mounting (Body Tapped, Body through-hole)

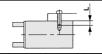


Model	Applicable bolts	Max. tightening torque (N·m)	Max. screw-in depth (Lmm)
MHY2-10D	M3 x 0.5	0.88	6
MHY2-16D	M4 x 0.7	2.1	8
MHY2-20D	M5 x 0.8	4.3	10
MHY2-25D	M6 x 1	7.4	12

Body through-hole

Model	Applicable bolts	Max. tightening torque (N·m)
MHY2-10D	M3 x 0.5	0.88
MHY2-16D	M4 x 0.7	2.1
MHY2-20D	M5 x 0.8	4.3
MHY2-25D	M6 x 1	7.4

Vertical Mounting (Body Tapped)



Model	Applicable bolts	Max. tightening torque (N·m)	Max. screw-in depth (Lmm)
MHY2-10D	M3 x 0.5	0.59	4
MHY2-16D	M4 x 0.7	1.3	5
MHY2-20D	M5 x 0.8	3.3	8
MHY2-25D	M6 x 1	5.9	10

How to Mount the Attachment to the Finger



(1) To mount the attachment to the finger, make sure to use a wrench to support the attachment so as not to apply undue strain on the finger.

(2) Refer to the table below for the proper tightening torque on the bolt used for securing the attachment to the finger.

Model	Applicable bolts	Max. tightening torque (N·m)
MHY2-10D MHY2-16D	M3 x 0.5	0.59
MHY2-20D	M4 x 0.7	1.4
MHY2-25D	M5 x 0.8	2.8

Operating Environment/ MHY2 Series

▲Caution

MHY2-25D Ø26H9 *

Use caution for the anti-corrosiveness of finger guide section.

Martensitic stainless steel is used for the finger. However, be aware that its anti-corrosion performance is inferior to austenitic stainless steel. In particular, the finger might be rusted in an environment where water droplets are adhered to it due to dew condensation.



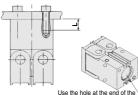
MHY2/MHW2 Series Specific Product Precautions 2

Be sure to read this before handling the products.

Mounting Air Grippers/MHW2 Series

Possible to mount from 3 directions.

Axial Mounting (Body Tapped)



Use the hole at the end of th body for positioning, etc.

Model	Applicable bolts		ghtening e (N⋅m)	Max. screw-in depth (Lmm)
MHW2-20D	M5 x 0.8	4	1.3	10
MHW2-25D	M6 x 1	7	7.4	12
MHW2-32D	M6 x 1	7	7.4	12
MHW2-40D	M8 x 1.25	10	7.7	15
MHW2-50D	M10 x 1.5	3	7.2	20
Model	Bore(mr	n)	Hole d	lepth (mm)
Model MHW2-20D	Bore(mr ø21H9 +0	<i>'</i>	Hole d	lepth (mm)
		052	Hole d	
MHW2-20D	ø21H9 +8	052	Hole d	3
MHW2-20D MHW2-25D	ø21H9 +0 ø26H9 +0	052 052 062	Hole d	3 3
MHW2-20D MHW2-25D MHW2-32D	ø21H9 *0 ø26H9 *0 ø34H9 *0	052 052 062 062	Hole d	3 3 4

Lateral mounting (Body Tapped, Body through-hole)

Body tapped



Model	Applicable bolts	Max. tightening torque (N·m)	Max. screw-in depth (Lmm)
MHW2-20D	M5 x 0.8	4.3	10
MHW2-25D	M6 x 1	7.4	12
MHW2-32D	M6 x 1	7.4	12
MHW2-40D	M8 x 1.25	17.7	16
MHW2-50D	M10 x 1.5	37.2	20

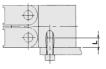
Body through-hole



Model	Applicable bolts	Max. tightening torque (N·m)
MHW2-20D	M4 x 0.7	2.1
MHW2-25D	M5 x 0.8	4.3
MHW2-32D	M5 x 0.8	4.3
MHW2-40D	M6 x 1	7.4
MHW2-50D	M8 x 1.25	17.7

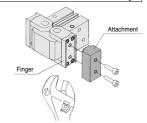
SMC

Vertical Mounting (Body Tapped)



Model	Applicable bolts	Max. tightening torque (N·m)	Max. screw-in depth (Lmm)
MHW2-20D	M5 x 0.8	2.9	7
MHW2-25D	M6 x 1	5.9	10
MHW2-32D	M6 x 1	5.9	10
MHW2-40D	M8 x 1.25	17.7	15
MHW2-50D	M10 x 1.5	37.2	20

How to Mount the Attachment to the Finger



 To mount the attachment to the finger, make sure to use a wrench to support the attachment so as not to apply undue strain on the finger.
 Refer to the table below for the proper tightening torque on the bolt used for securing the attachment to the finger.

Applicable bolts	Max. tightening torque (N·m)
M4 x 0.7	1.4
M5 x 0.8	2.5
M6 x 1	4.1
M8 x 1.25	10.6
M10 x 1.5	24.5
	M4 x 0.7 M5 x 0.8 M6 x 1 M8 x 1.25

MHZ

MHF

MHR Mhk Mhs

MHC

MHT

MHY MHW -X MRHQ MA D-