



Operation Manual

PRODUCT NAME

Air Gripper for Collaborative Robots

MODEL / Series / Product Number

JMHZ2-16D-X7400B-(DTP/HC10DT/HC10)-(N/P)

SMC Corporation

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Safety Instructions

These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions indicate the level of potential hazard with the labels of “Caution,” “Warning” or “Danger.” They are all important notes for safety and must be followed in addition to International Standards (ISO/IEC)*1), and other safety regulations.

*1) ISO 4414: Pneumatic fluid power -- General rules relating to systems.

ISO 4413: Hydraulic fluid power -- General rules relating to systems.

IEC 60204-1: Safety of machinery -- Electrical equipment of machines.(Part 1: General requirements)

ISO 10218: Manipulating industrial robots -Safety.

etc.



Caution

Caution indicates a hazard with a low level of risk which, if not avoided, could result in minor or moderate injury.



Warning

Warning indicates a hazard with a medium level of risk which, if not avoided, could result in death or serious injury.



Danger

Danger indicates a hazard with a high level of risk which, if not avoided, will result in death or serious injury.

Warning

1. The compatibility of the product is the responsibility of the person who designs the equipment or decides its specifications.

Since the product specified here is used under various operating conditions, its compatibility with specific equipment must be decided by the person who designs the equipment or decides its specifications based on necessary analysis and test results.

The expected performance and safety assurance of the equipment will be the responsibility of the person who has determined its compatibility with the product.

This person should also continuously review all specifications of the product referring to its latest catalog information, with a view to giving due consideration to any possibility of equipment failure when configuring the equipment.

2. Only personnel with appropriate training should operate machinery and equipment.

The product specified here may become unsafe if handled incorrectly.

The assembly, operation and maintenance of machines or equipment including our products must be performed by an operator who is appropriately trained and experienced.

3. Do not service or attempt to remove product and machinery/equipment until safety is confirmed.

1. The inspection and maintenance of machinery/equipment should only be performed after measures to prevent falling or runaway of the driven objects have been confirmed.

2. When the product is to be removed, confirm that the safety measures as mentioned above are implemented and the power from any appropriate source is cut, and read and understand the specific product precautions

of all relevant products carefully.

3. Before machinery/equipment is restarted, take measures to prevent unexpected operation and malfunction.

4. Contact SMC beforehand and take special consideration of safety measures if the product is to be used in any of the following conditions.

1. Conditions and environments outside of the given specifications, or use outdoors or in a place exposed to direct sunlight.

2. Installation on equipment in conjunction with atomic energy, railways, air navigation, space, shipping, vehicles, military, medical treatment, combustion and recreation, or equipment in contact with food and beverages, emergency stop circuits, clutch and brake circuits in press applications, safety equipment or other applications unsuitable for the standard specifications described in the product catalog.

3. An application which could have negative effects on people, property, or animals requiring special safety analysis.

4. Use in an interlock circuit, which requires the provision of double interlock for possible failure by using a mechanical protective function, and periodical checks to confirm proper operation.



Safety Instructions

Caution

The product is provided for use in manufacturing industries.

The product herein described is basically provided for peaceful use in manufacturing industries. If considering using the product in other industries, consult SMC beforehand and exchange specifications or a contract if necessary.
If anything is unclear, contact your nearest sales branch.

Limited warranty and Disclaimer/Compliance Requirements

The product used is subject to the following “Limited warranty and Disclaimer” and “Compliance Requirements”.

Read and accept them before using the product.

Limited warranty and Disclaimer

1. The warranty period of the product is 1 year in service or 1.5 years after the product is delivered, whichever is first.
Also, the product may have specified durability, running distance or replacement parts. Please consult your nearest sales branch.
2. For any failure or damage reported within the warranty period which is clearly our responsibility, a replacement product or necessary parts will be provided.
This limited warranty applies only to our product independently, and not to any other damage incurred due to the failure of the product.
3. Prior to using SMC products, please read and understand the warranty terms and disclaimers noted in the specified catalog for the particular products.

Compliance Requirements

1. The use of SMC products with production equipment for the manufacture of weapons of mass destruction (WMD) or any other weapon is strictly prohibited.
2. The export of SMC products or technology from one country to another is governed by the relevant security laws and regulations of the countries involved in the transaction. Prior to the shipment of an SMC product to another country, ensure that all local rules governing that export are known and followed.

Caution

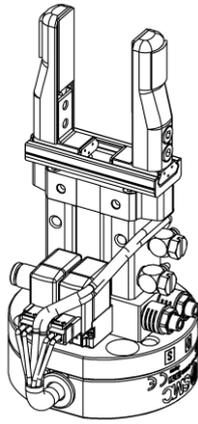
SMC products are not intended for use as instruments for legal metrology.

Measurement instruments that SMC manufactures or sells have not been qualified by type approval tests relevant to the metrology (measurement) laws of each country.

Therefore, SMC products cannot be used for business or certification ordained by the metrology (measurement) laws of each country.

1. List of included items

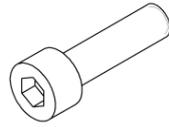
JMHZ2-16D-X7400B-DTP-(N/P)



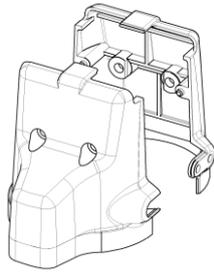
Air gripper 1pc.



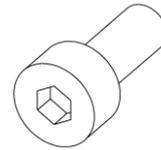
Positioning pin (6x10)1pc.
For positioning the product



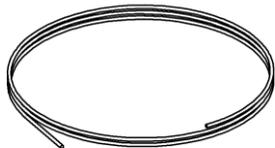
Hexagon socket head cap screw (M6x23) 4pcs.
For mounting the product.



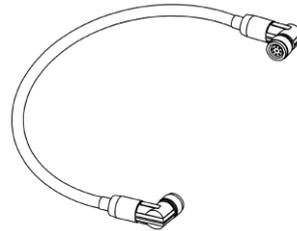
Protection cover (Valve side) 1pc.
Protection cover (Switch side) 1pc.



Hexagon socket head cap screw (M4x10) 4pcs.
For mounting the cover.



Polyurethane tube for piping $\phi 4$
(TU0425BU-100) 2m.



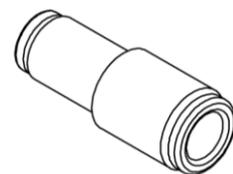
Conversion cable 1pc.



One touch fittings (KQ2L04-M5A1) 2pcs.

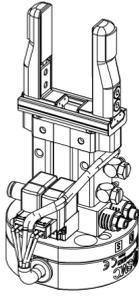


One touch fittings (KQ2L06-08A) 1pc.



One touch fittings (KQ2H04-06A) 1pc.

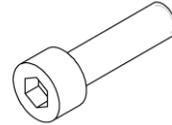
JMHZ2-16D-X7400B-HC10DT, HC10-(N/P)



Air gripper 1pc.



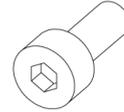
Parallel pin (6x10) 1pc.
For positioning the product.



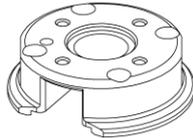
Hexagon socket head cap screw (M6x23) 4pcs.
For mounting the product.



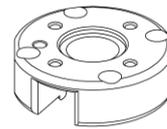
Protection cover (Valve side) 1pc.
Protection cover (Switch side) 1pc.



Hexagon socket head cap screw (M4x10) 4pcs. For mounting the cover.



Flange for MOTOMAN-HC10 1pc.
* For JMHZ2-16D-X7400B-HC10-(*).



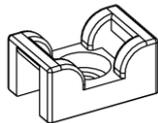
Flange for MOTOMAN-HC10DT 1pc.
* For JMHZ2-16D-X7400B-HC10DT-(*).



Hexagon socket head cap screw (M6x12) 4pcs. For mounting the flange.



Parallel pin (6x10mm) 1pc.
For positioning the flange.



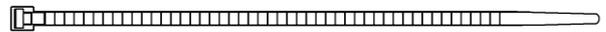
INSULOK® tie mount 2pcs.



Hexagon socket head cap screw (M4x8) 2pcs.
For fixing INSULOK® tie mount.



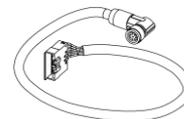
Cross recessed resin round head screw (M4x6) 2pcs.
For plugging when INSULOK® cable tie fixtures are not used.



INSULOK® tie 2pcs.



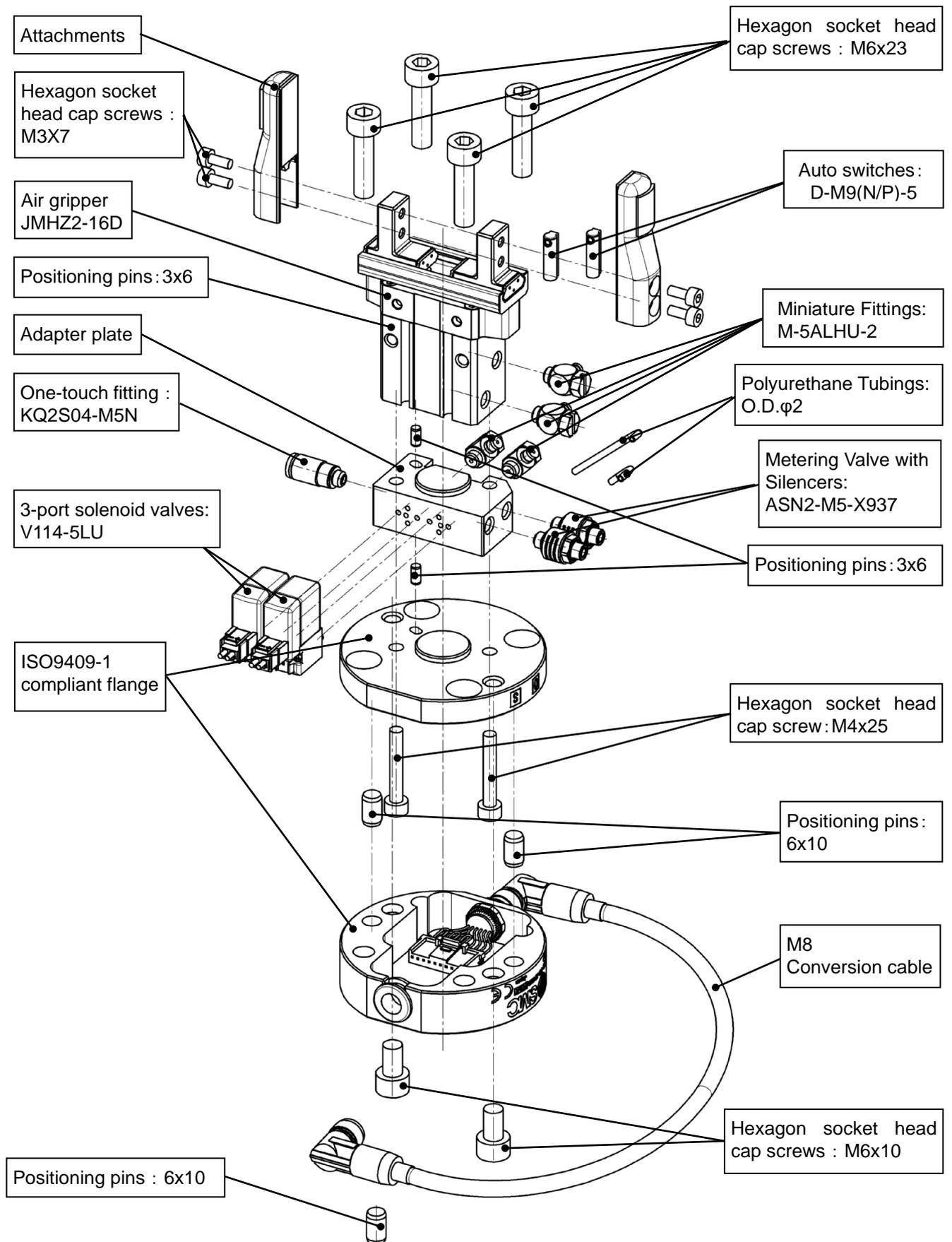
Coil tube for piping φ4 (TU0425BU-100) 2m.



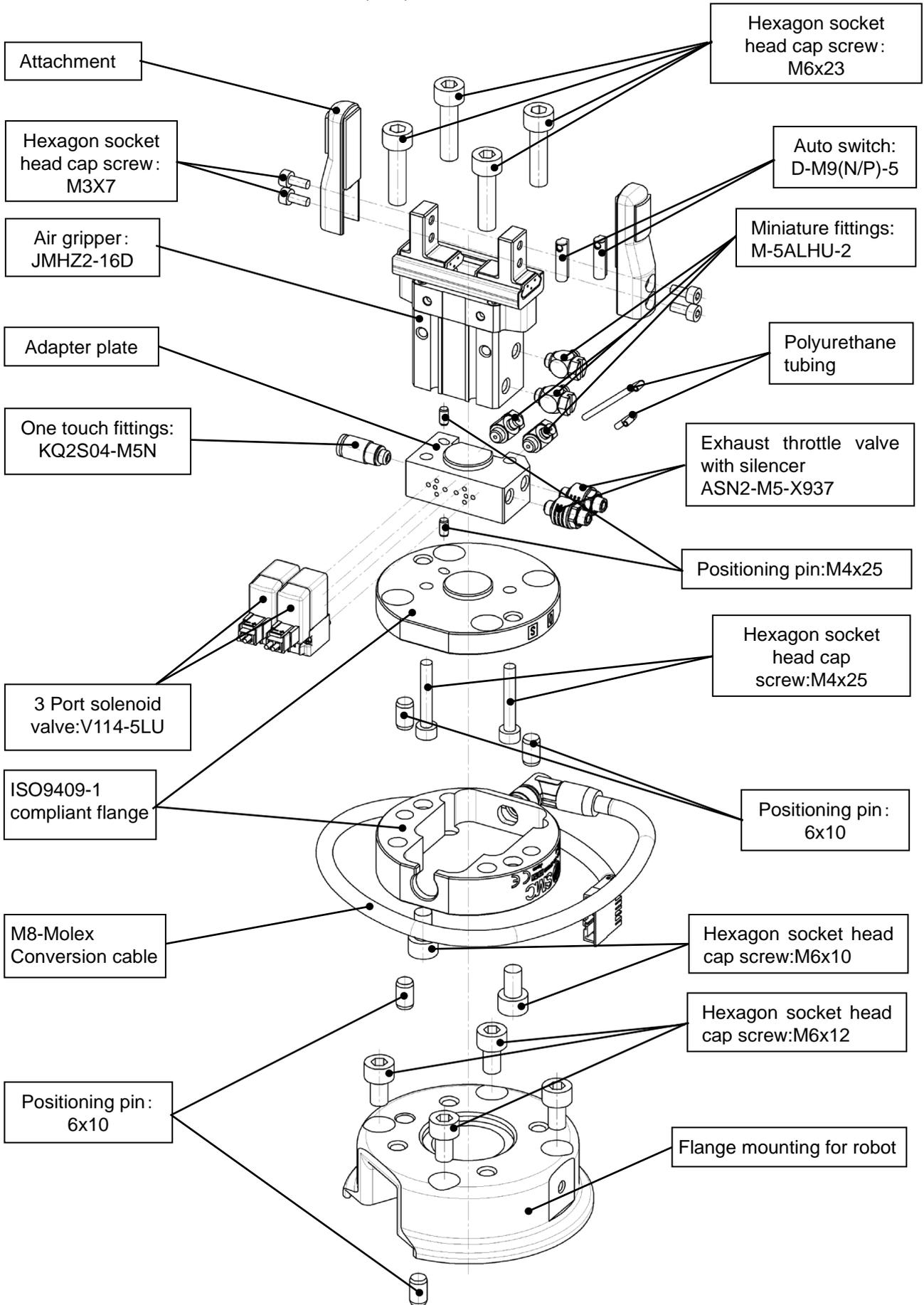
M8-Molex Conversion cable 1pc.

2. Parts description of the air gripper

JMHZ2-16D-X7400B-DTP-(N/P)



JMHZ2-16D-X7400B-HC10DT、HC10-(N/P)



3. Product Specifications

3-1. How to order

JMHZ2 - 16 D - X7400B - DTP - N

● Bore size

φ16

● Compatible robot

DTP	MOTOMAN-10DTP,20DTP,20SDTP
HC10DT	MOTOMAN-HC10DT
HC10	MOTOMAN-HC10

● Auto switch output method

No.	Auto switch No.	Medium	QTY
N	D-M9N-5	NPN	2
P	D-M9P-5	PNP	2

3-2. Specifications

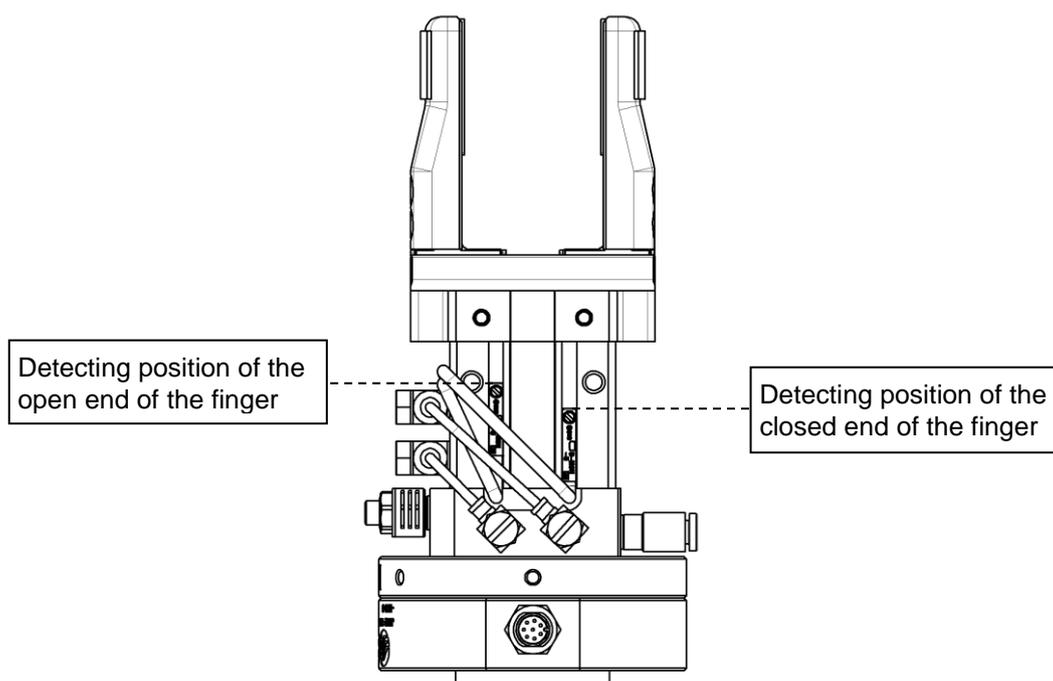
Specifications

		JMHZ2-16D-X7400B -DTB-(N/P)	JMHZ2-16D-X7400B- HC10DT-(N/P)	JMHZ2-16D-X7400B HC10-(N/P)
Cylinder inside diameter (mm)		16		
Fluid		Air		
Operating pressure (MPa)		0.1 to 0.7		
Ambient and operating fluid temperature(°C)		-10 to 50		
Repeatability (mm)		±0.01		
Maximum operating frequency (c.p.m.)		120		
Lubrication		Non-lube		
Operating method		Double acting		
Gripping force Actual value per finger (N)	External gripping force	32.7		
	Internal Gripping force	43.5		
Opening/ closing stroke (both sides) (mm)		10		
Weight (g)		440	720	
Connector configuration of the accessory		M8 8 pin connector (Socket)	One side M8 8 pin connector(Socket) One side Connector made by MOLEX(51227-0800)	

*The sensing position of the auto switch is fixed to the open end and closed end of the finger.

* When detecting the gripping position of the workpiece, secure the auto switch at the appropriate position according to the shape of the workpiece.

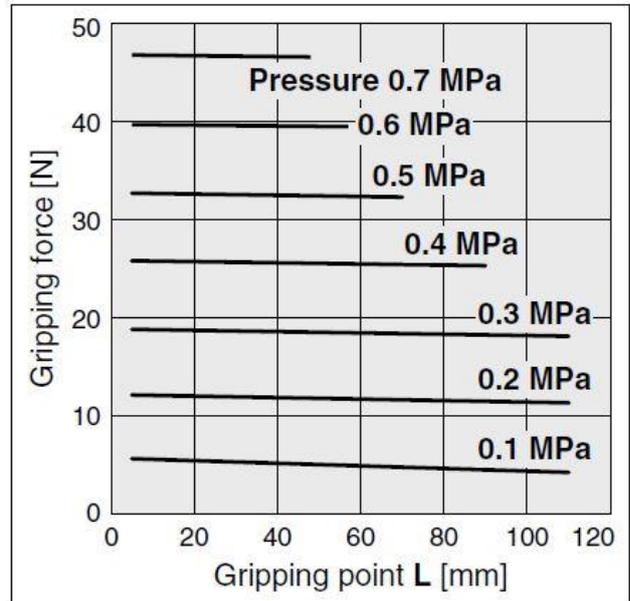
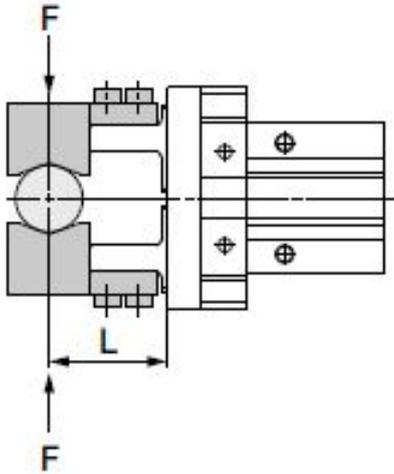
* For examples of setting auto switch and setting of mounting position of auto switches, please refer to the JMHZ2 Series catalogue P.15 onwards on our website (www.smcworld.com).



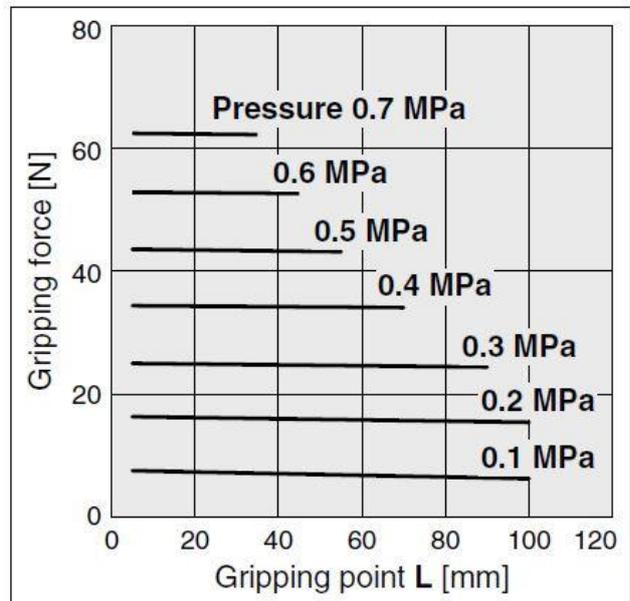
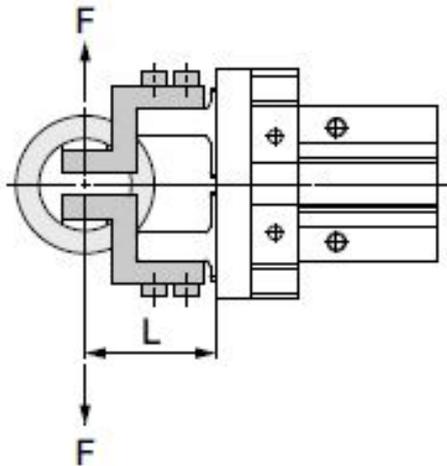
3-3. Gripping force

The gripping force shown in the graph to the right represents the gripping force of one finger when all fingers and attachments are in contact with the workpiece.

External gripping state.



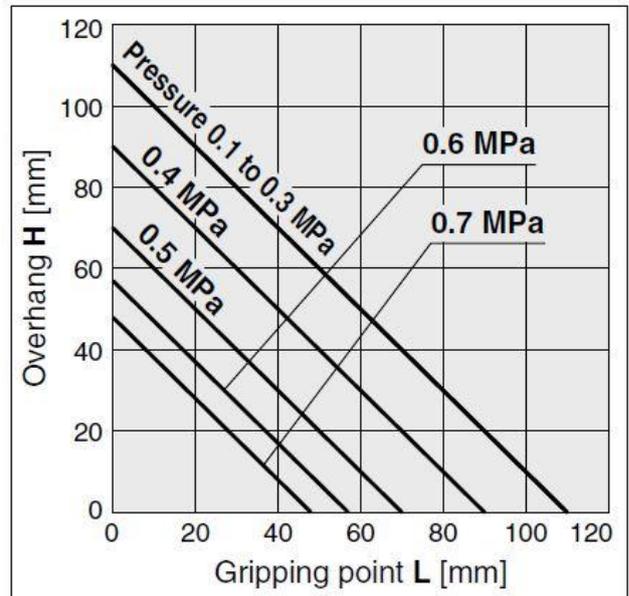
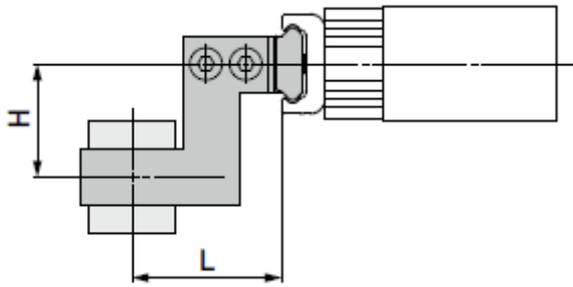
Internal gripping state.



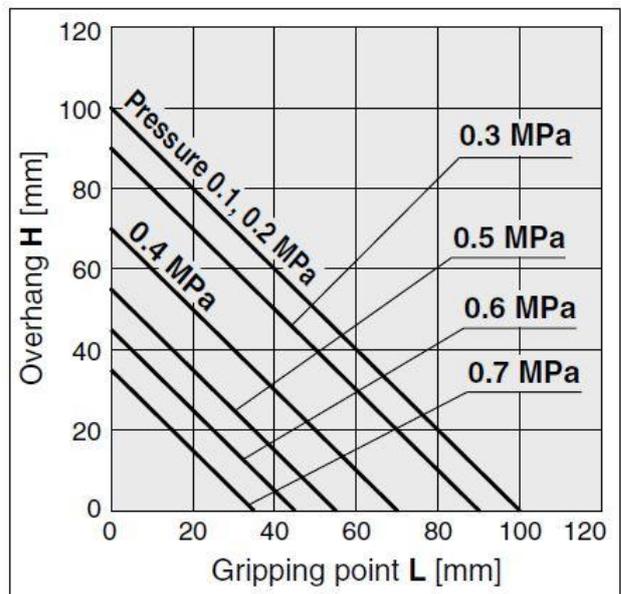
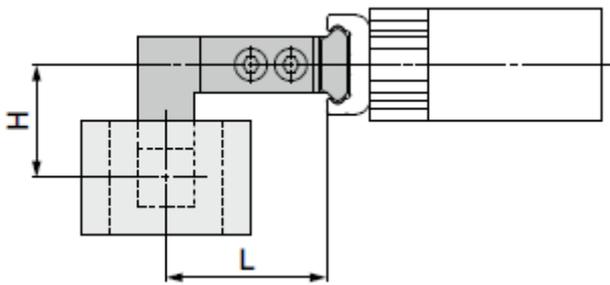
3-4. Gripping point

The air gripper should be operated so that the workpiece gripping point “L” and the amount of overhang “H” stay within the range shown for each operating pressure given in the graphs to the right. If the workpiece gripping point goes beyond the range limits, this will have an adverse effect on the life of the air gripper.

External gripping state



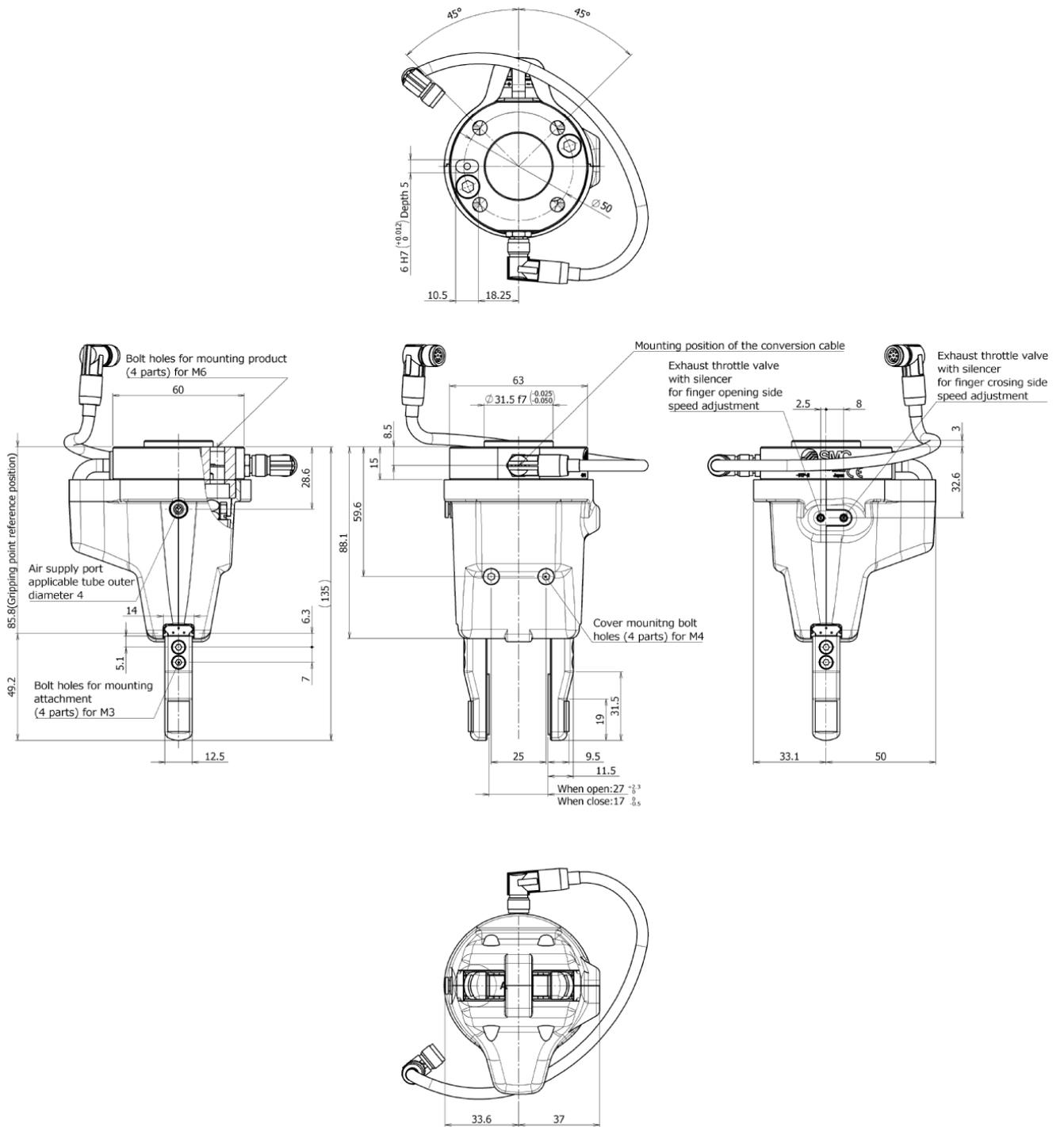
Internal gripping state



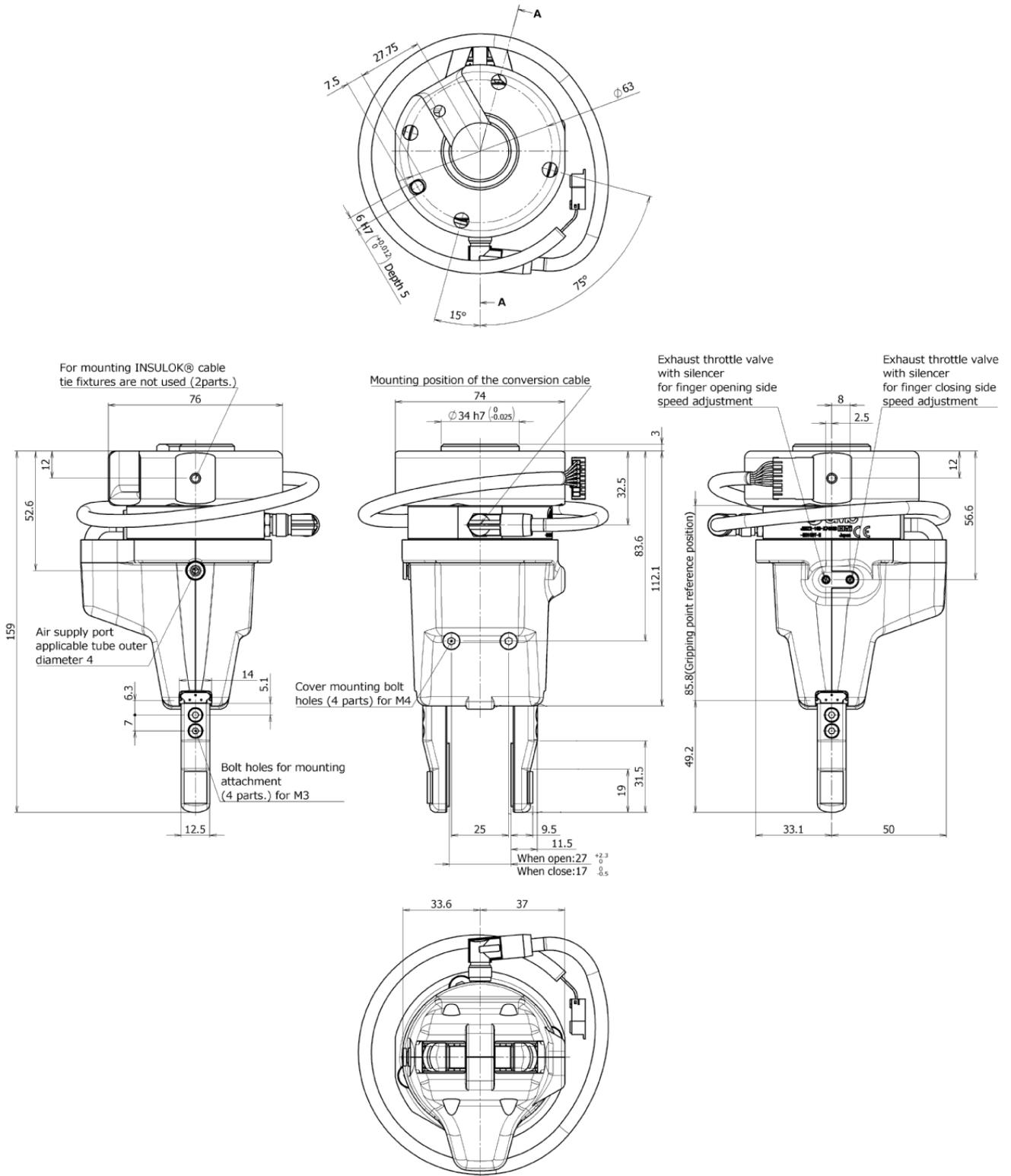
3-5. Dimensions

3-5-1. JMHZ2-16D-X7400B-DTP-(N/P)

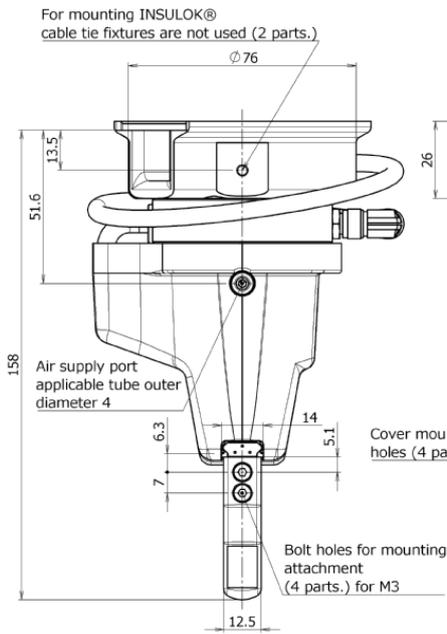
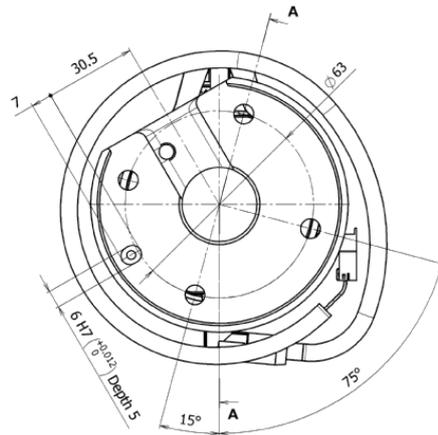
Refer to P17, P18 and P19 for the dimensions of the air gripper, valves and auto switch.



3-5-2. JMHZ2-16D-X7400B-HC10DT-(N/P)



3-5-3. JMHZ2-16D-X7400B-HC10-(N/P)

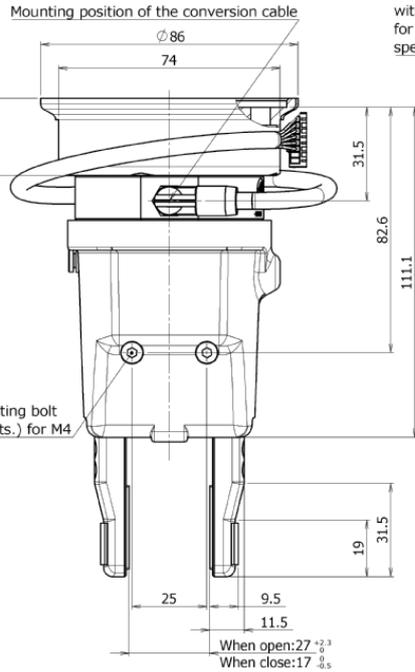


For mounting INSULOK® cable tie fixtures are not used (2 parts.)

Air supply port applicable tube outer diameter 4

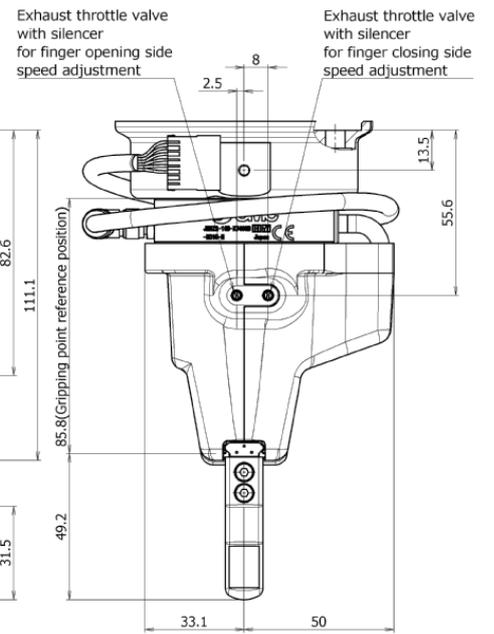
Bolt holes for mounting attachment (4 parts.) for M3

Cover mounting bolt holes (4 parts.) for M4



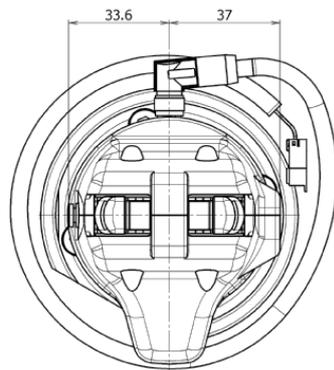
Mounting position of the conversion cable

When open: 27^{+2.3}
When close: 17^{-8.5}



Exhaust throttle valve with silencer for finger opening side speed adjustment

Exhaust throttle valve with silencer for finger closing side speed adjustment

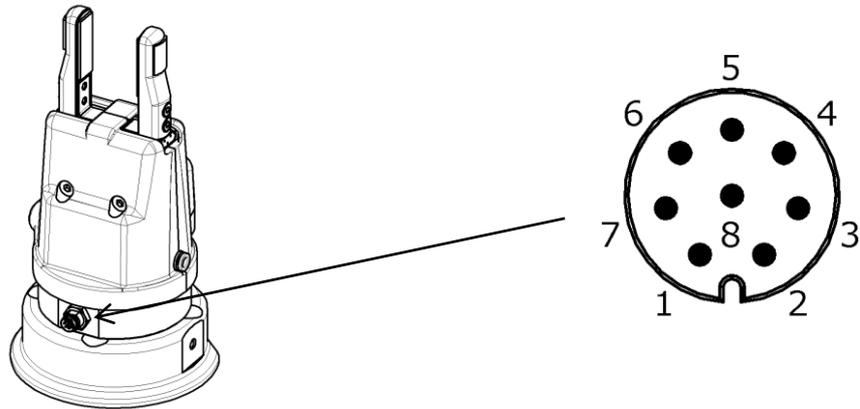


3-6. Connector and pin layout

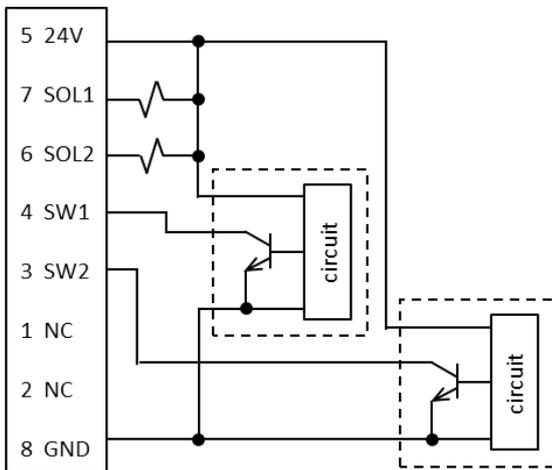
M8 8 pin connector is fixed to the product.

Connect the communication cable correctly. Refer to P.22 and P.26 for assembling method.

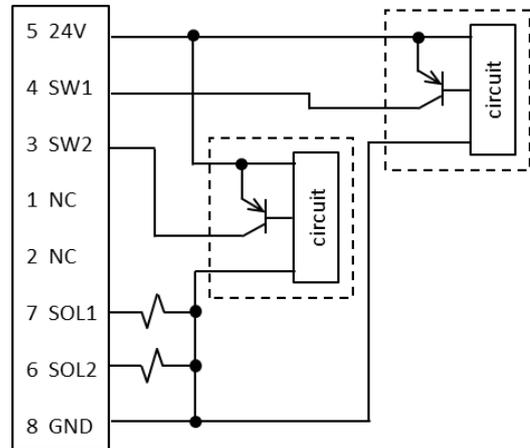
3-6-1. JMHZ2-16D-X7400B-DTP-(N/P)



NPN output

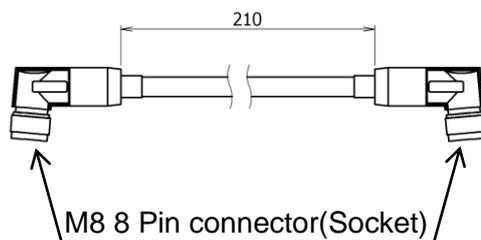


PNP output

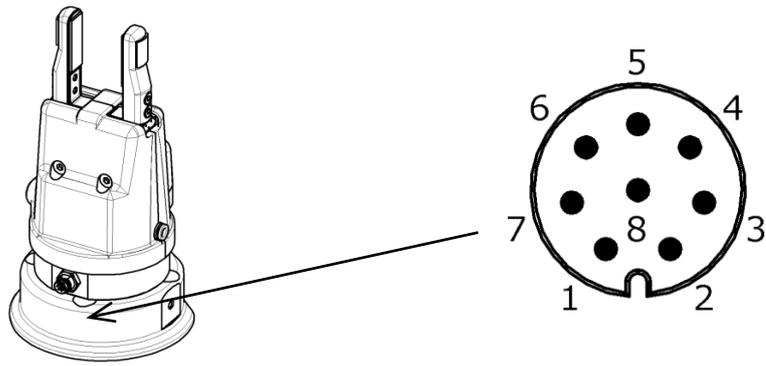


PIN No.	Function	Explanation
1	-	-
2	-	-
3	Auto switch(Finger closing side)	-
4	Auto switch(Finger closing side)	-
5	+24V	Power supply for 24 VDC
6	Valve ON/OFF(Finger closing side)	-
7	Valve ON/OFF(Finger opening side)	-
8	GND	Power supply for 0 VDC

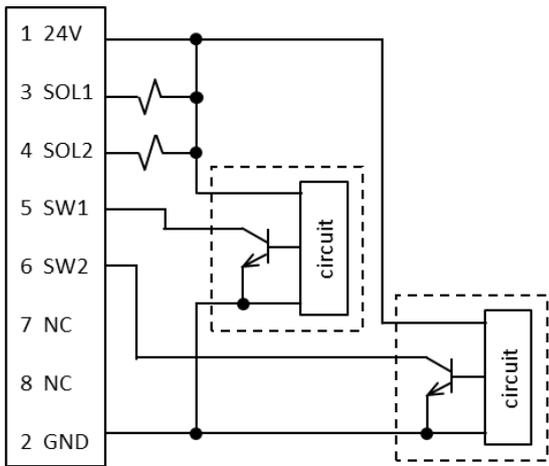
Conversion cable



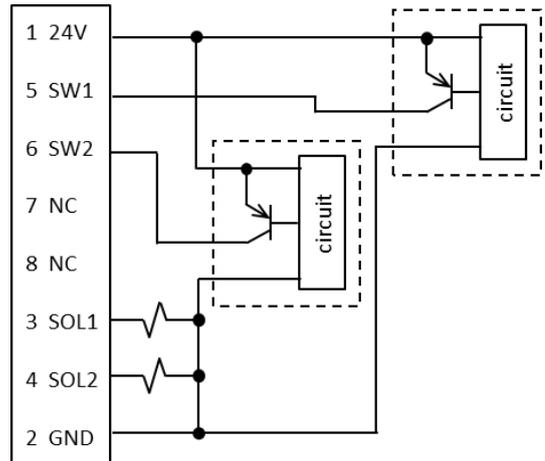
3-6-2. JMHZ2-16D-X7400B-(HC10DT/HC10)-(N/P)



NPN output

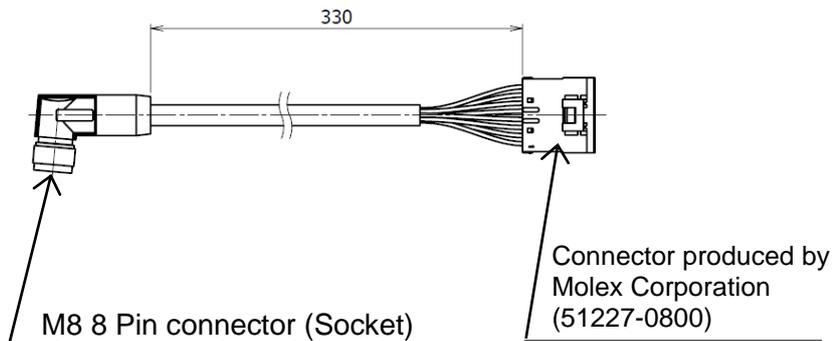


PNP output

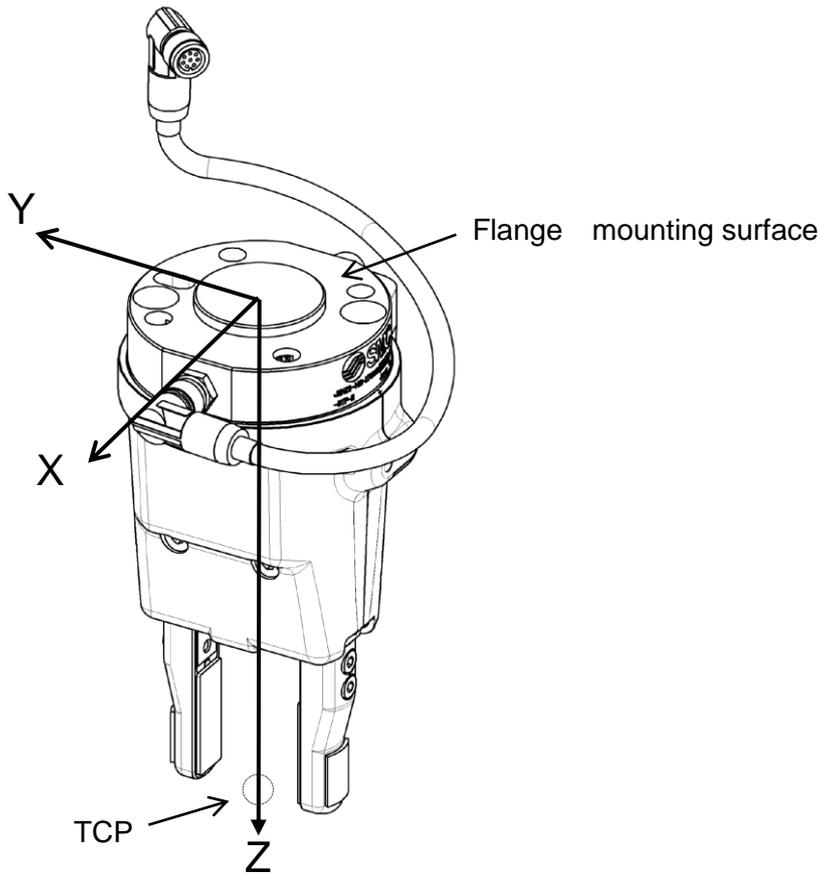


PIN No.	Function	Explanation
1	+24V	Power supply for 24 VDC
2	GND	Power supply for 0 VDC
3	Valve ON/OFF(Finger opening side)	-
4	Valve ON/OFF(Finger closing side)	-
5	Valve ON/OFF(Finger opening side)	-
6	Valve ON/OFF(Finger closing side)	-
7	-	-
8	-	-

Conversion cable



3-7. Center of gravity



*Figure shows case JMHZ2-16D-X7400B-DTP-(N/P).

	JMHZ2-16D-X7400B-DTP			JMHZ2-16D-X7400B -HC10DT			JMHZ2-16D-X7400B -HC10		
	X	Y	Z	X	Y	Z	X	Y	Z
Center of gravity(mm)	2.4	0.0	42.6	-0.4	-0.8	48.4	-0.4	-0.8	47.4
Tool center point(TCP)	X	Y	Z	X	Y	Z	X	Y	Z
	0	0	135	0	0	159	0	0	158

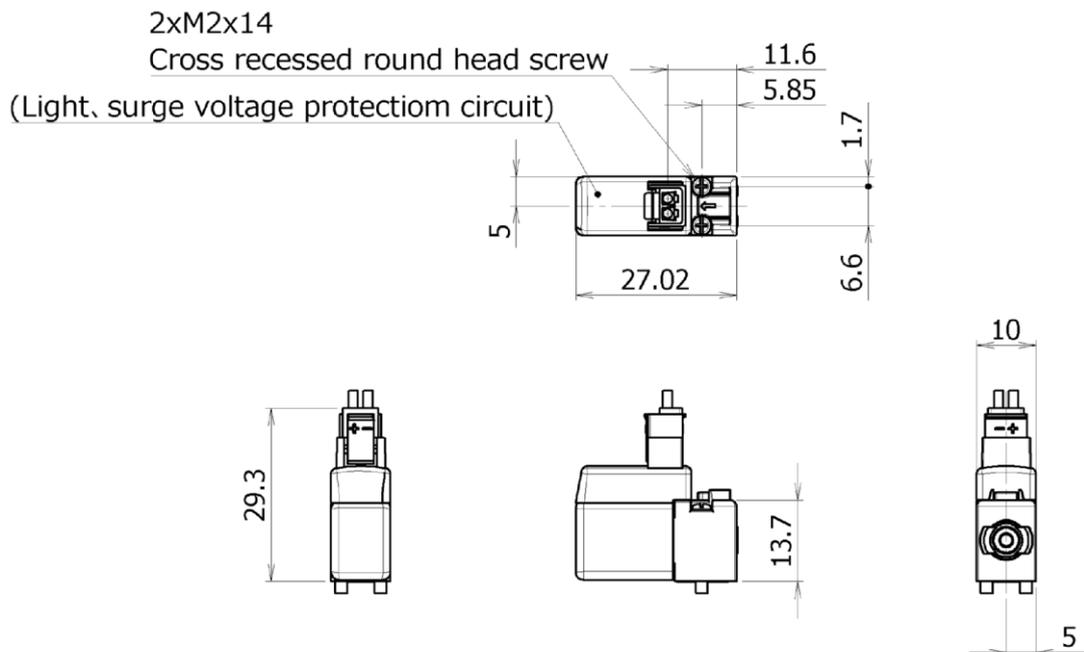
4-2. 3-port solenoid valve

Specifications

Model No.	V114-5LU
Fluid	Air
Ambient and operating fluid temperature(°C)	-10 to 50 (No freezing)
Response time [ms]	ON : 5 or less OFF : 4 or less
Minimum operation frequency [Hz]	20
Lubrication	No
Mounting orientation	Free
Impact resistance/Vibration resistance (m/s ²)	150/30
Enclosure rating	Dustproof

Solenoid specifications

Model No.	V114-5LU
Electrical entry	L shaped plug connector (L)
Coil rated voltage [V]	24
Allowable voltage fluctuation	-10 to 10%
Power consumption [W]	0.4 [Starting 0.4, Holding 0.1]
Surge voltage suppressor	varistor
Indicator LED	LED



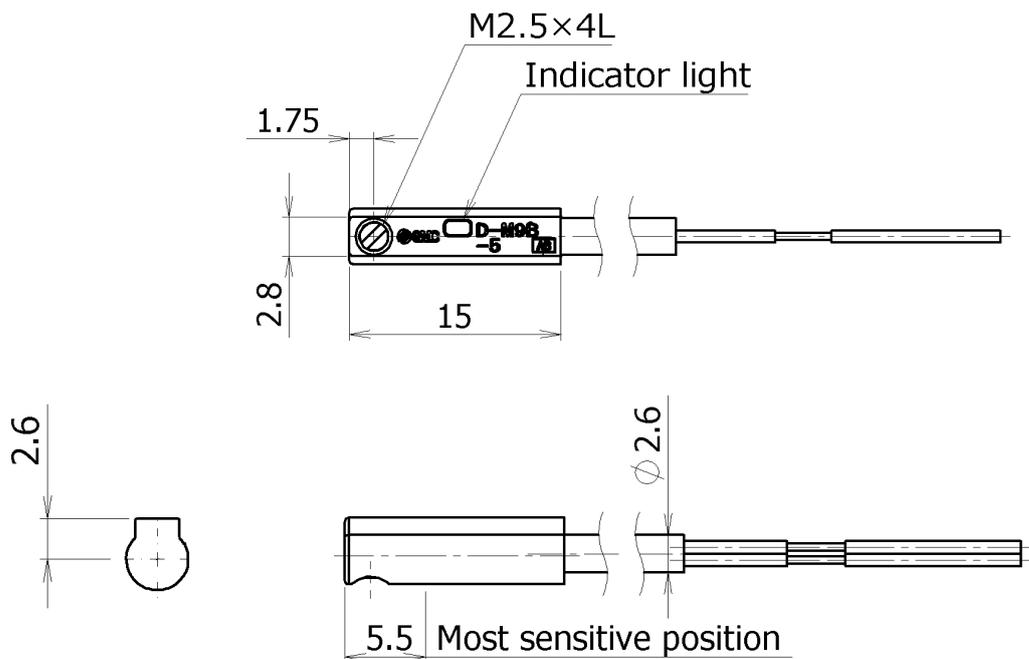
4-3. Auto switch

Auto Switch Specifications

D-M9□-5(With indicator light)		
Auto switch model	D-M9N-5	D-M9P-5
Electrical entry direction	In-line	
Wiring	3-wire	
Output	NPN type	PNP type
Applicable load	IC circuit, Relay, PLC	
Power supply voltage	5 , 12 , 24 VDC (4.5 to 28 V)	
Current consumption	10 mA or less	
Load voltage	28 VDC or less	-
Load current	40 mA or less	
Internal voltage drop	0.8 V or less at 10 mA (2 V or less at 40 mA)	
Current leakage	100 μA or less at 24 VDC	
Indicator LED	Red LED illuminates when turned ON.	
Standard	CE marking、RoHS	

Dimensions

D-M9□-5



5. Operating method or operation

5-1. Precautions for Design

Warning

1. The product is designed for use only in compressed air systems. Do not operate at pressures or temperatures, etc., beyond the range of the specifications, as this can cause damage or malfunction of the cylinder and other equipment. (Refer to the specifications.)
Please contact SMC if using fluids other than compressed air. The product cannot be guaranteed if is used outside of the specification range.
2. Take safety measures (e.g. mounting protective covers) when there is a danger of fingers being caught in a gripper or workpieces causing damage, etc.
3. There is a danger of workpieces dropping if there is a decrease in gripping force due to a drop in circuit pressure caused by a power failure, etc. It is necessary to take measures such as drop prevention so that injury and damage to machinery or equipment can be prevented.
4. If the product is used for a purpose other than the transportation of a workpiece such as positioning or clamping, please consult SMC.

Caution

1. Finite orbit type guide is used in the actuator finger part. By using this, when there are inertial force which cause by movements or rotation to the actuator, steel ball will move to one side and this will cause a large resistance degrade the accuracy. When there are inertial force which cause by movements or rotation to the actuator, operate the finger to full stroke.

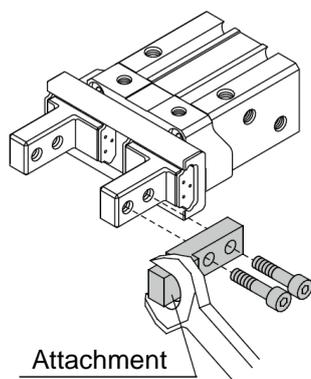
5-2. Installation

Warning

1. Install and operate the product only after reading the Operation Manual carefully and understanding its contents. Also, keep the manual where it can be referred to as necessary.
2. When installing the products, allow access for maintenance.
3. Do not scratch or dent the air gripper by dropping or bumping it when mounting.
Slight deformation can cause inaccuracies or a malfunction.
4. Tighten the screw within the specified torque range when mounting the attachment.
Tightening with a torque above the limit can cause malfunction, while insufficient tightening can cause slippage and dropping.

How to mount attachment to the finger

Make sure to mount the attachments on fingers with the tightening torque in the table below by using bolts, etc., for the female threads on fingers.



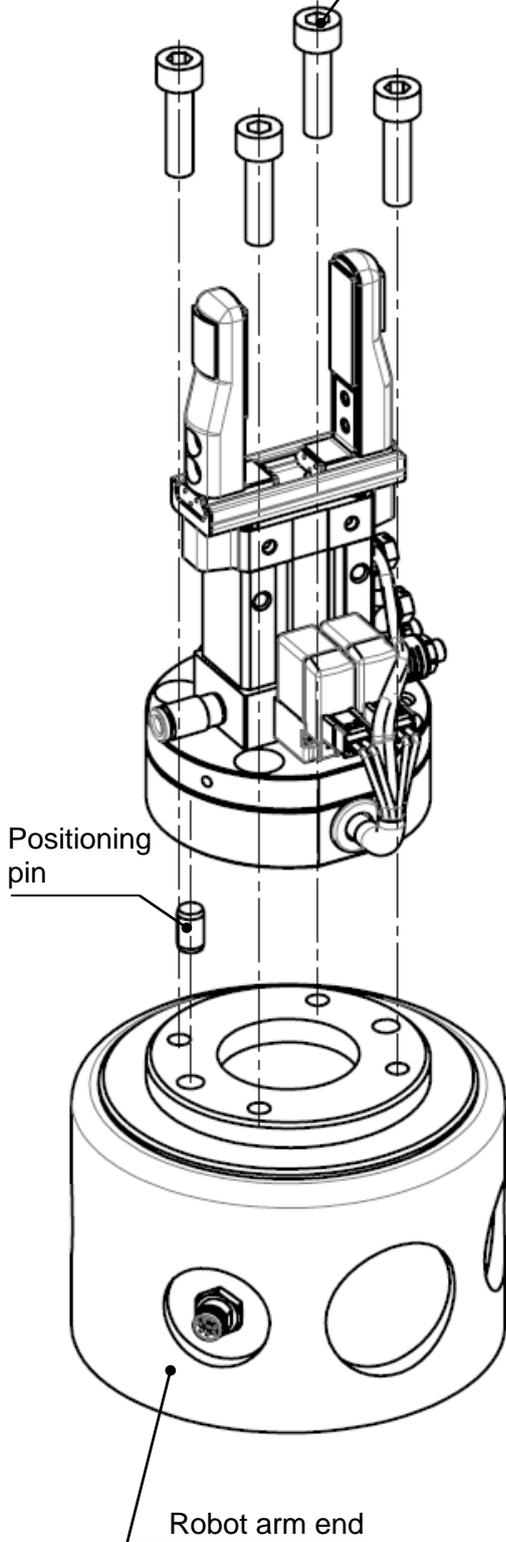
Model	Bolt	Max.tightening Torgue (Nm)
JMHZ2-16D	M3 x 0.5	0.59

How to Mount Air Gripper

(1) Mounting orientation: On robot arm(s)

Hexagon socket head cap screw(M6 x 23)

Max. tightening torque:
5.2 Nm

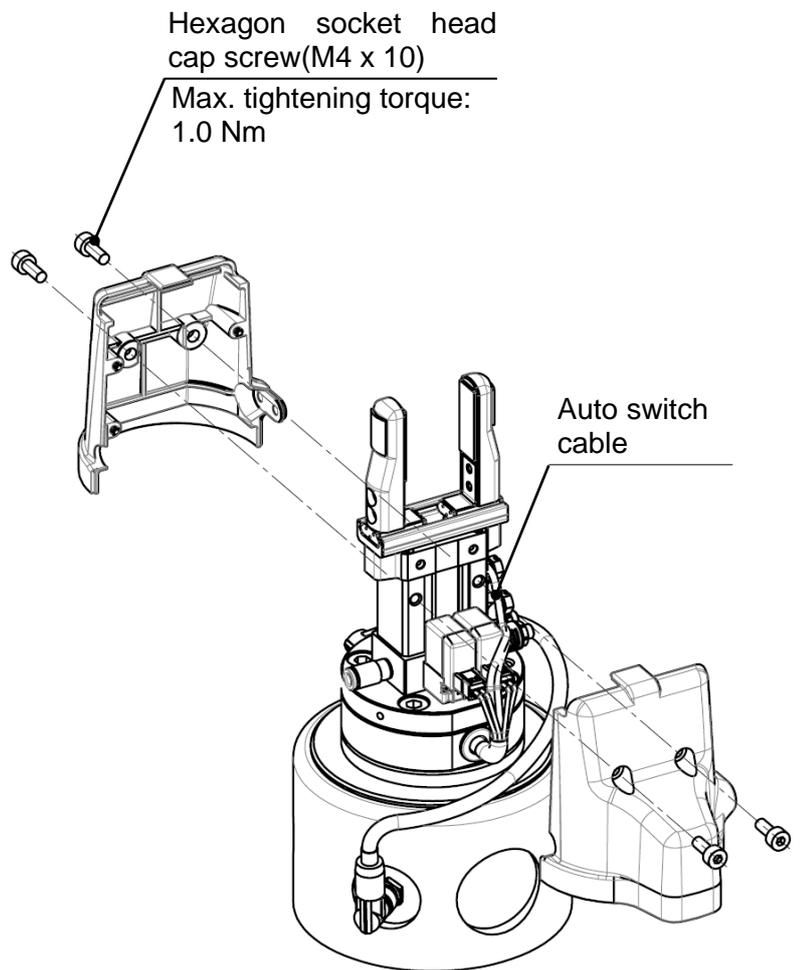


(2) Mounting to the cover

Take care not to get the switch cable caught when mounting the cover.

Hexagon socket head cap screw(M4 x 10)

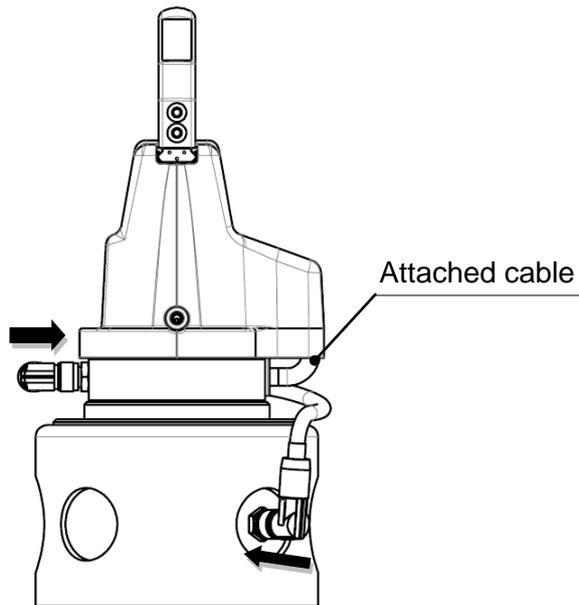
Max. tightening torque:
1.0 Nm



(3) Connecting the M8 connector

* Do not energize while securing the connector.

* Check that the connector is not loose.

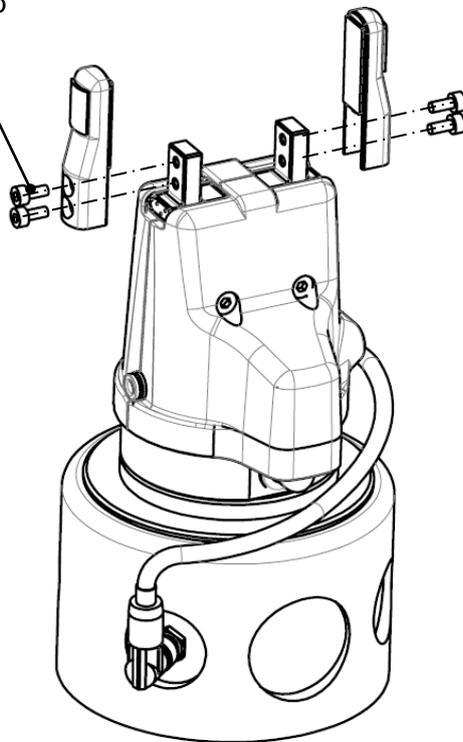


(4) For mounting attachment

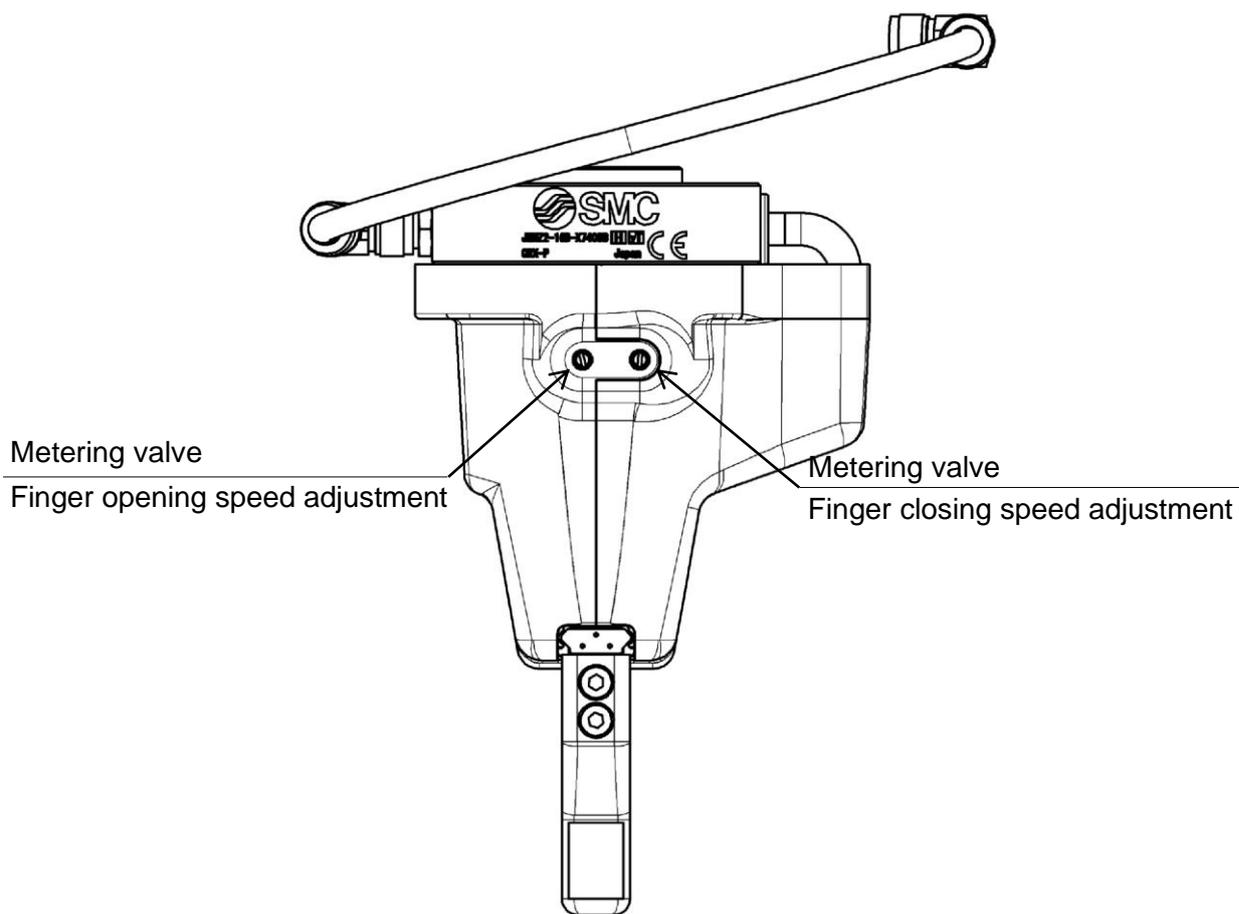
For mounting and removal of the attachment, refer to the drawing below. Refer to P20, "5-2 Installation" for mounting of the finger to the attachment.

Hexagon socket head cap screw(M3 x 7)

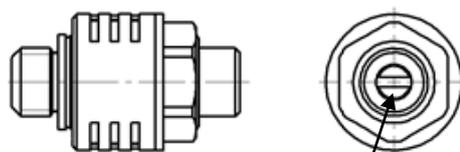
Max. tightening torque:
0.59 Nm



Finger open / close speed adjustment



Magnified view of the metering valve



Adjustment groove
(*for flat blade screwdriver
Blade width 0.7mm)

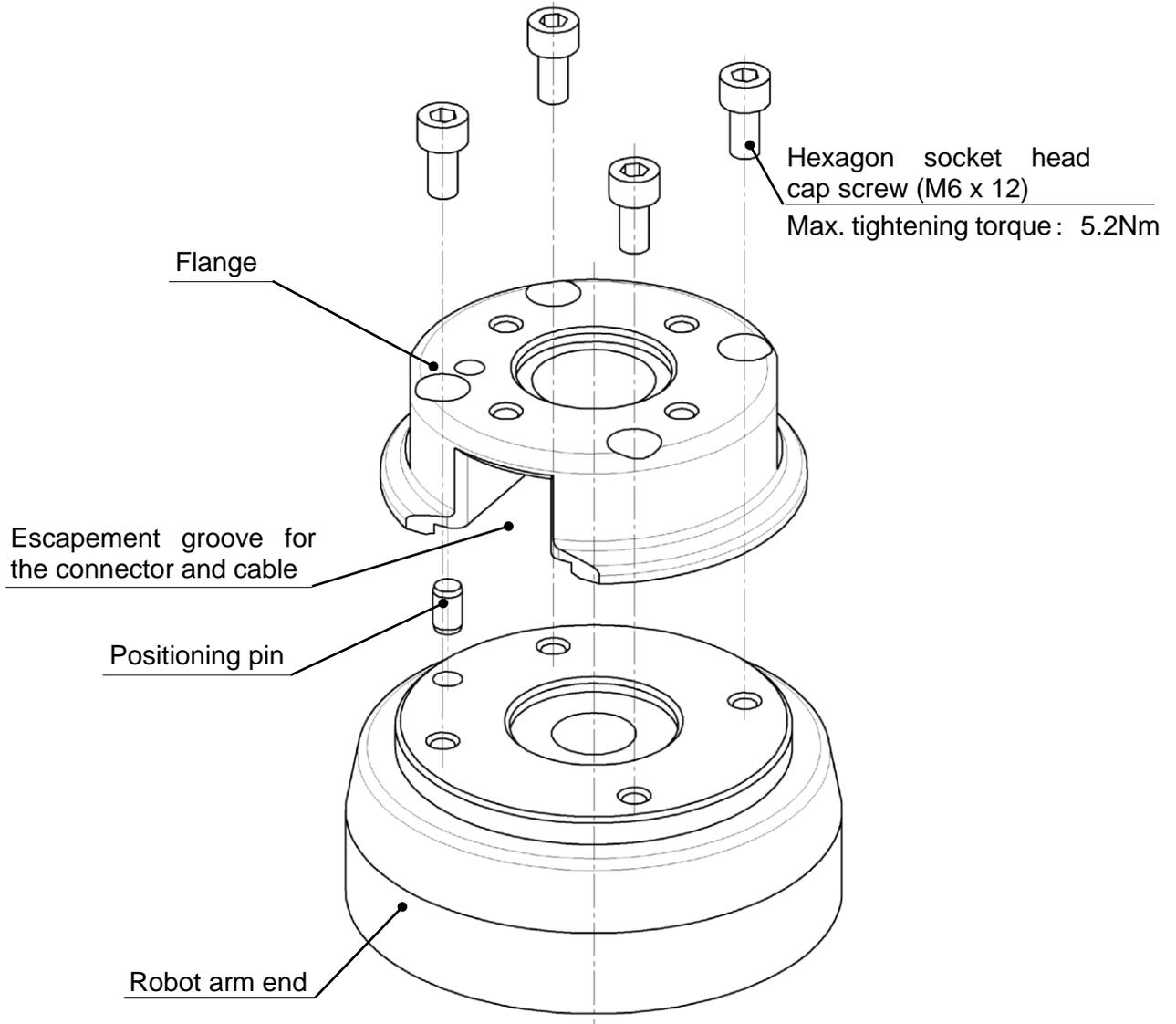
- * Use a flat blade screwdriver for adjusting the restriction of the metering valves.
- * Keep the restriction of the 2 metering valves approximately the same. If they are different too much, the operation may become unstable.

(1) Mounting orientation: On robot arm(s)

Adjust the robot arm position before mounting so that the mounting is easy.

- Let the connectors and cables coming out of the end of the robot arm out of the escapement groove of the flange.
- Make sure that the cable is not caught by the hexagon socket head cap screw when it is tightened.

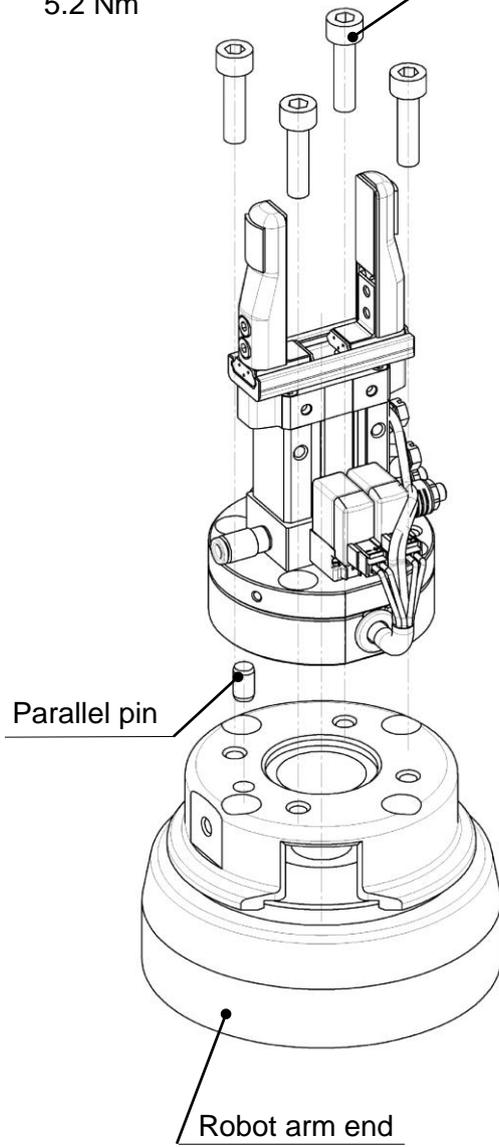
* The drawing shows the flange for MOTOMAN-HC10.



(2) Mounting to the flange

Hexagon socket head cap screw (M6 x 23)

Max. tightening torque: 5.2 Nm

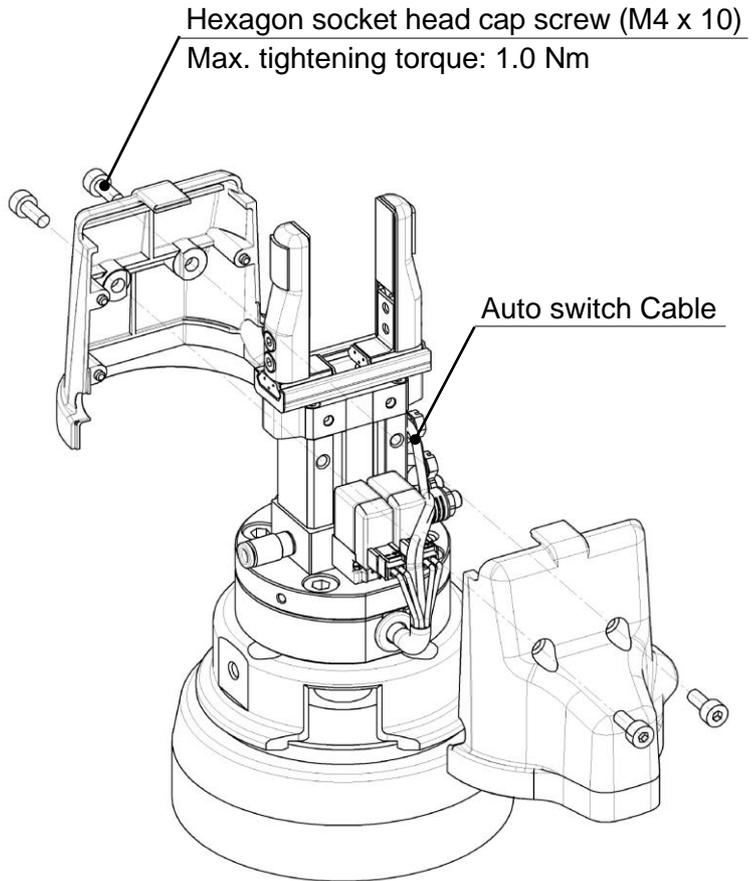


(3) Mounting to the cover

Take care not to get the switch cable caught when mounting the cover.

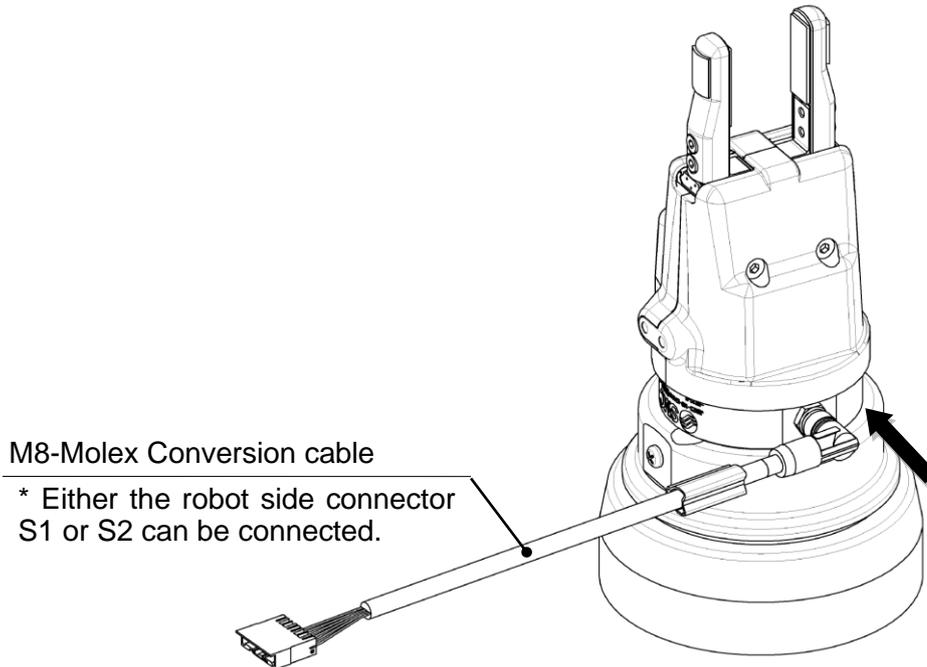
Hexagon socket head cap screw (M4 x 10)

Max. tightening torque: 1.0 Nm



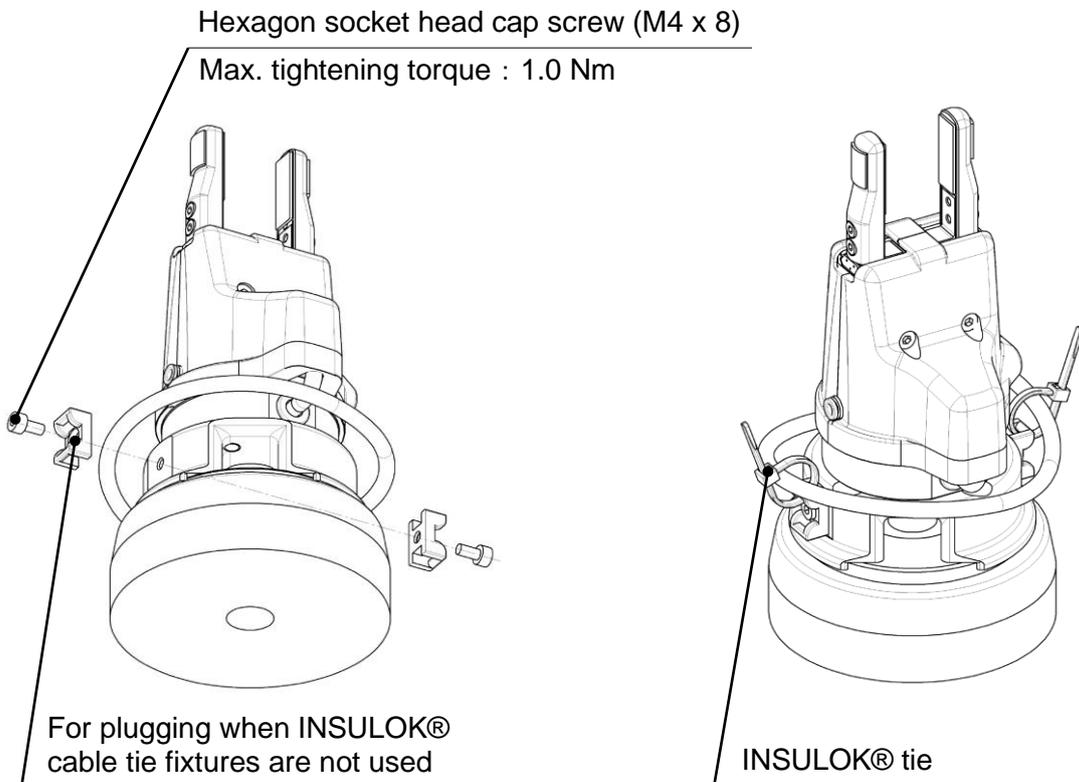
(4) Connecting the M8 connector

- Mount the conversion cable to the M8 connector.
- After mounting the conversion cable, connect the robot arm end connector and conversion cable connector.
- * Do not energize while securing the connector.
- * Check that the connector is not loose.



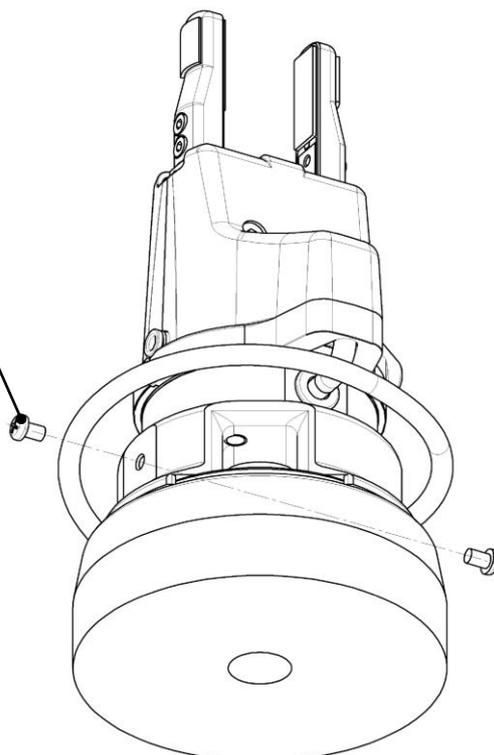
(5) Secure the cable

- Cable is secured by the INSULOK® tie and cable tie mount included in the accessories.
- * After securing the table, cut off the excessive part of the INSULOK® tie.



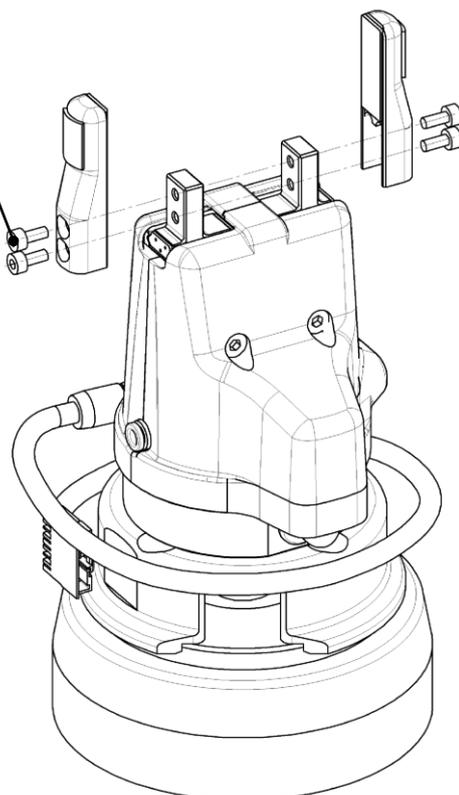
* Use a cross recessed resin round head screw (M4 x 6) as a plug when the INSULOK® cable tie is not used.

Cross recessed resin round head screw (M4 x 6)
Max. tightening torque 1.0Nm

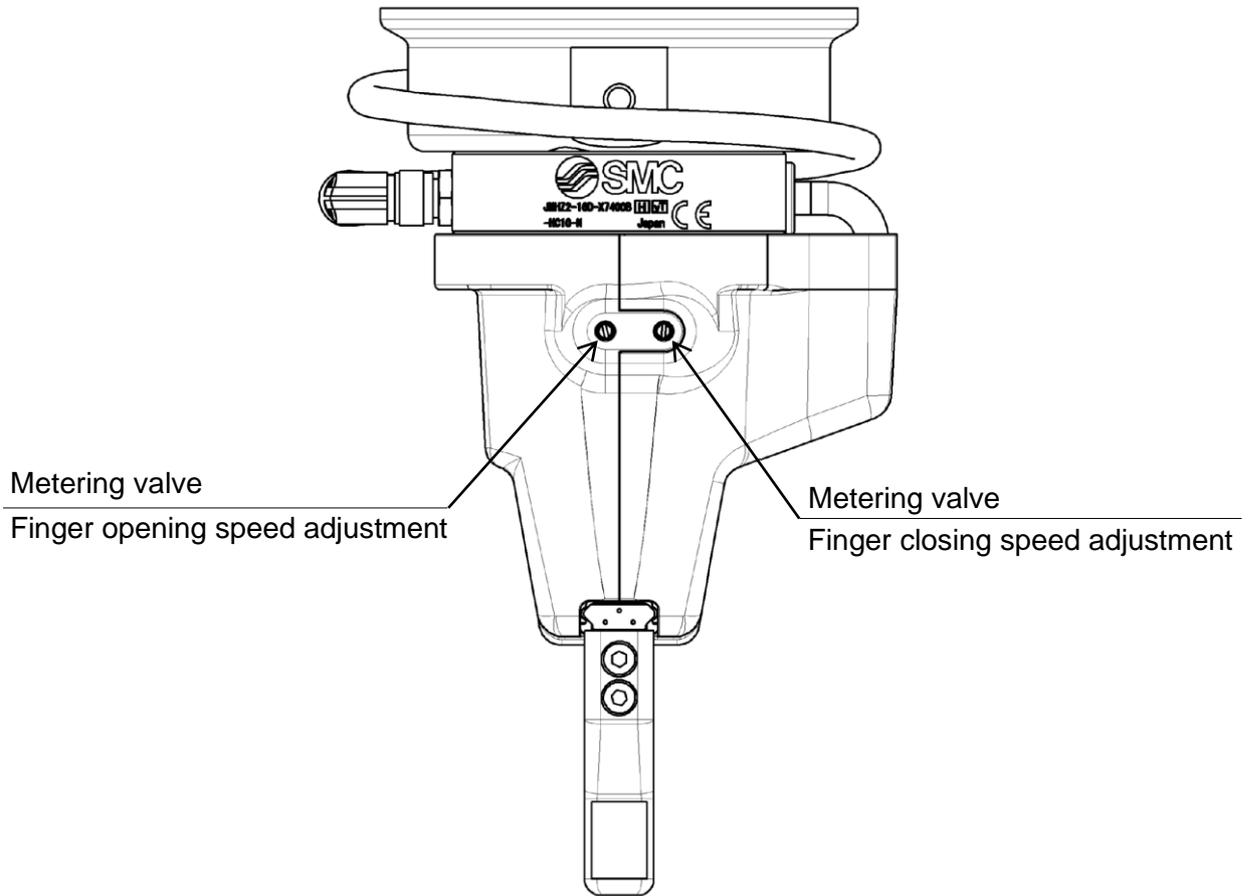


(6) For mounting attachment
For mounting and removal of the attachment, refer to the drawing below. Refer to P20, "5-2 Installation" for mounting of the finger to the attachment.

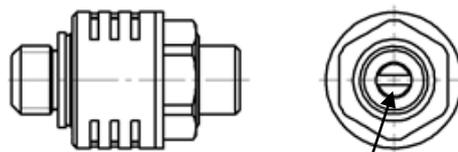
Hexagon socket head cap (M3 x 7)
Max. tightening torque: 0.59Nm



Finger open / close speed adjustment



Magnified view of the metering valve



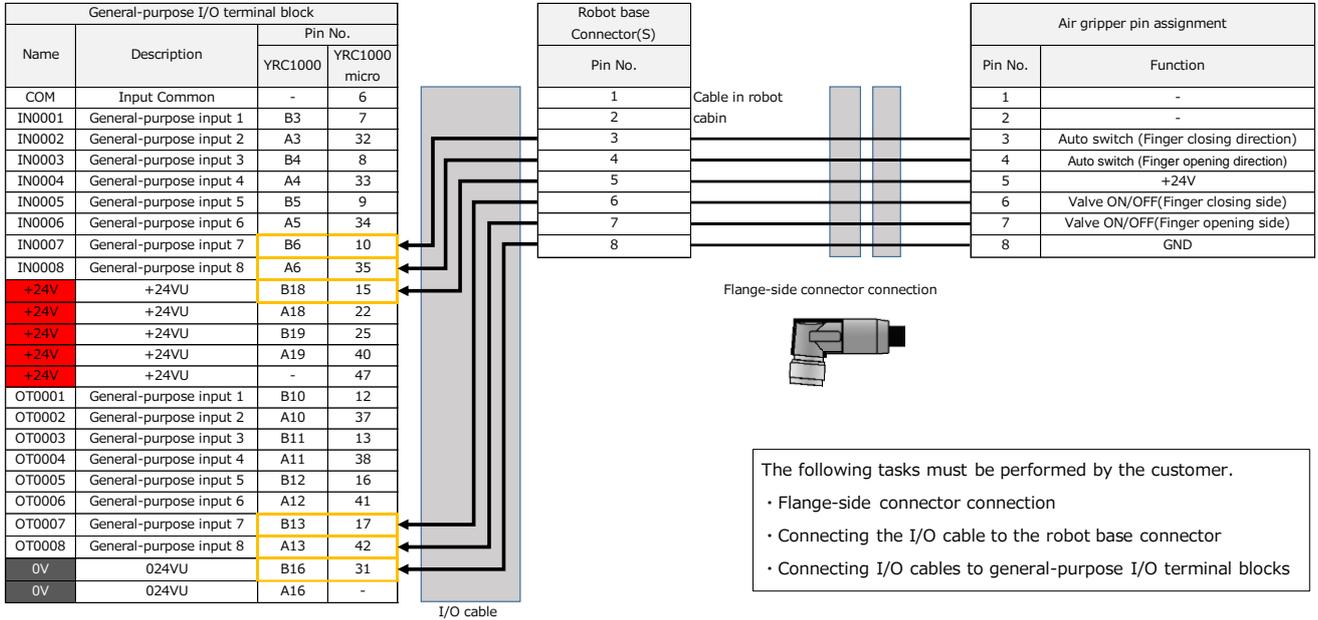
Adjustment groove
(*for flat blade screwdriver
Blade width 0.7mm)

- * Use a flat blade screwdriver for adjusting the restriction of the metering valves.
- * Keep the restriction of the 2 metering valves approximately the same. If they are different too much, the operation may become unstable.

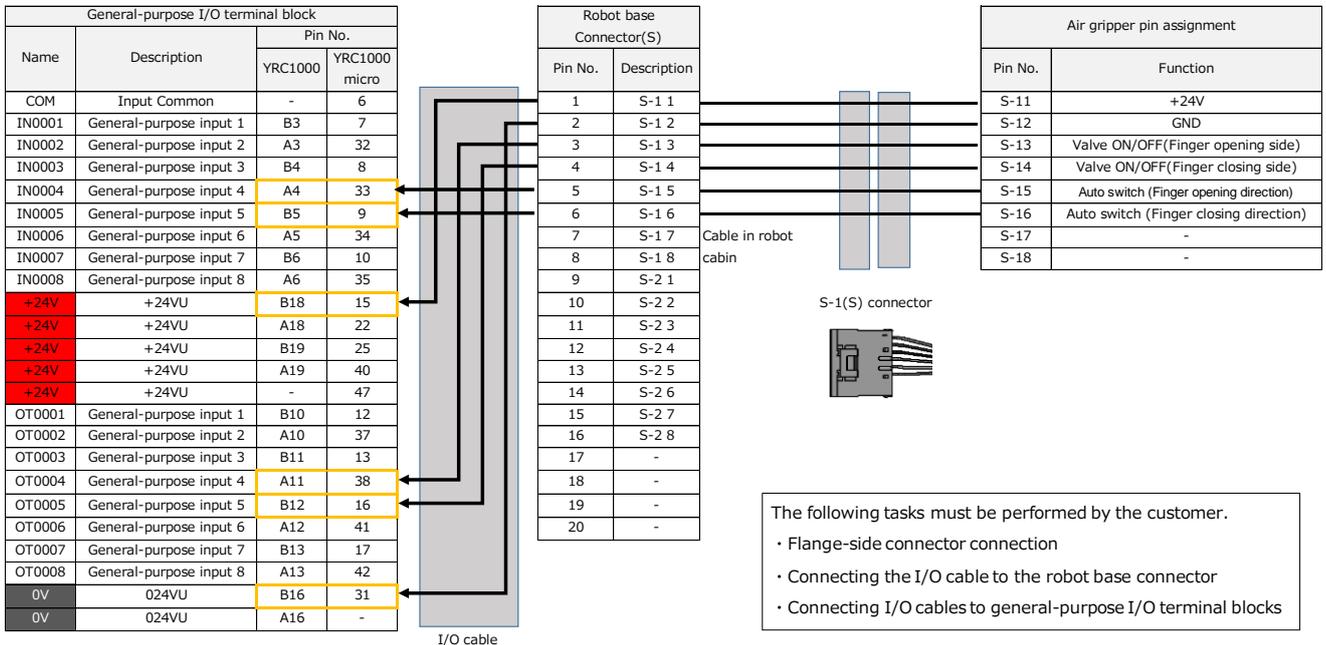
5-3. Wiring example to robot controller (common to NPN/PNP)

The table below shows wiring examples of I/O cables and general-purpose I/O terminal blocks. The Connector of I/O cables to the general-purpose I/O terminal block should be by the customer. Also, Before wiring, be sure to confirm whether the robot controller specifications are NPN or PNP.

In case of JMHZ2-16D-X7400B-DTP-(N/P)



In case of JMHZ2-16D-X7400B-HC10DT,HC10-(N/P)



5-4. YASKAWA Plug & Play Kit

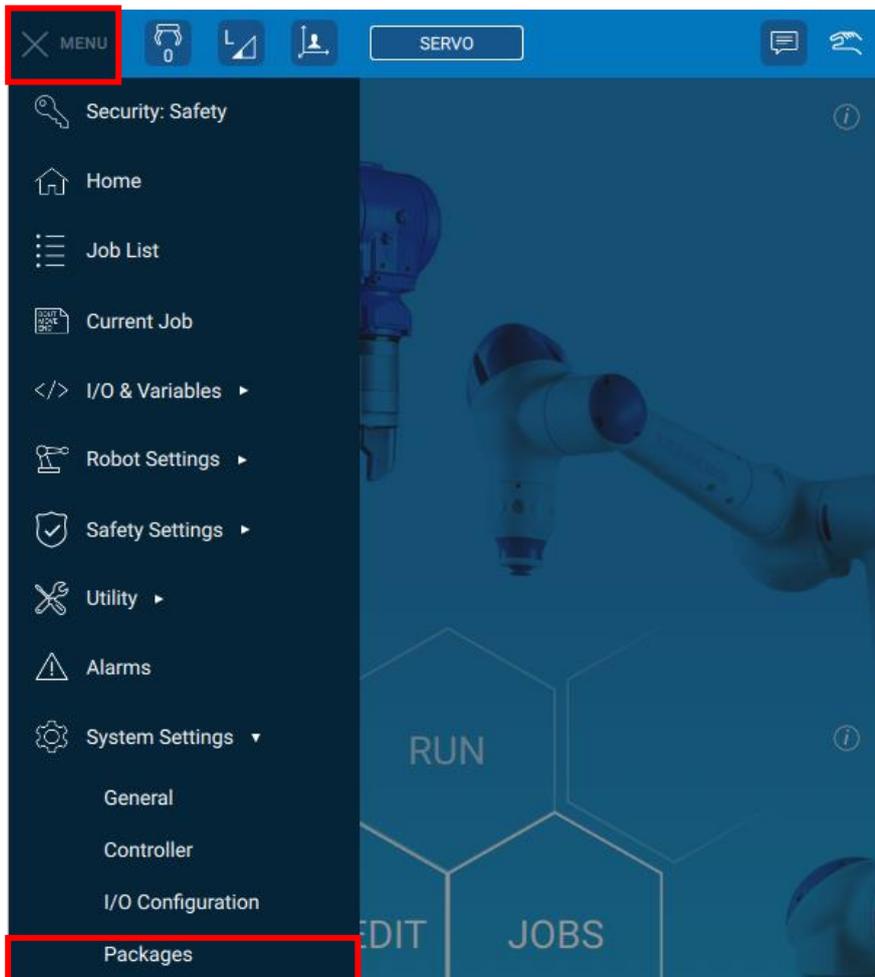
The YASKAWA Plug & Play Kit allows you to easily connect the air gripper to the robot and operate it.

5-4-1. Installing YASKAWA Plug & Play Kit

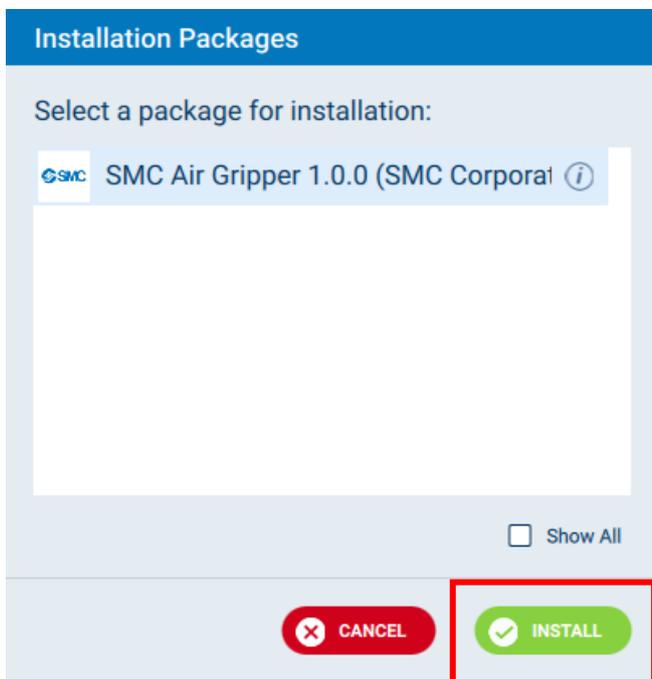
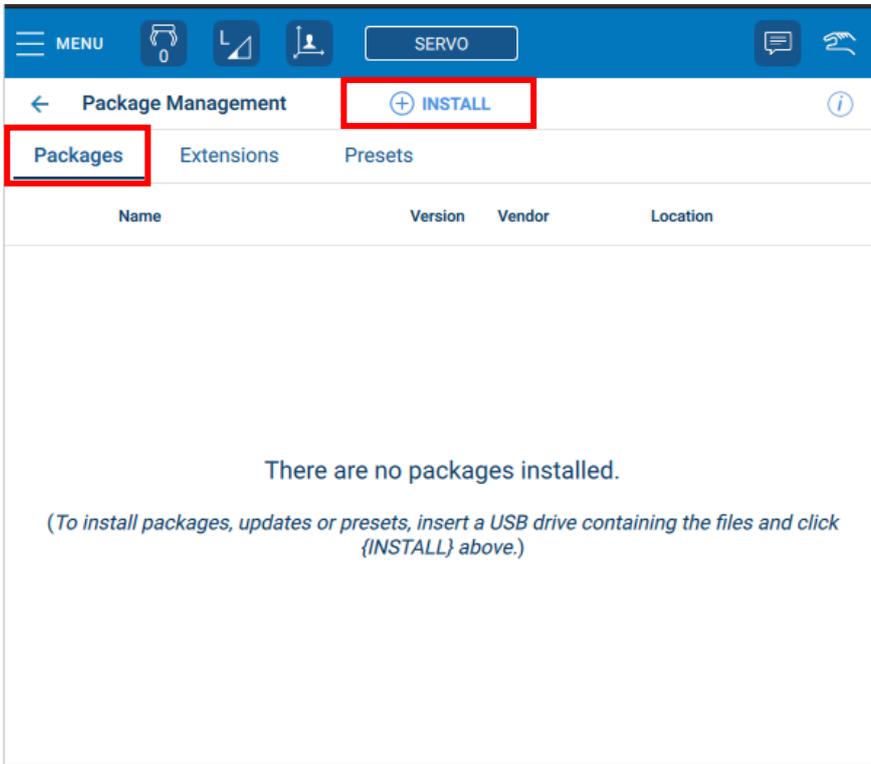
The YASKAWA Plug & Play Kit is installed by means of the YASKAWA Installation Packages(.yip) file.

* Set the security access level to the administration level.

- 1.Download YASKAWA Installation Packages “SmcAirGripperExt.yip” from the SMC website.
- 2.Copy the downloaded file to a USB memory stick, insert the stick to the USB port of the smart pendant, select [MENU] on the upper left of the screen, and tap [System settings] -> [Packages].

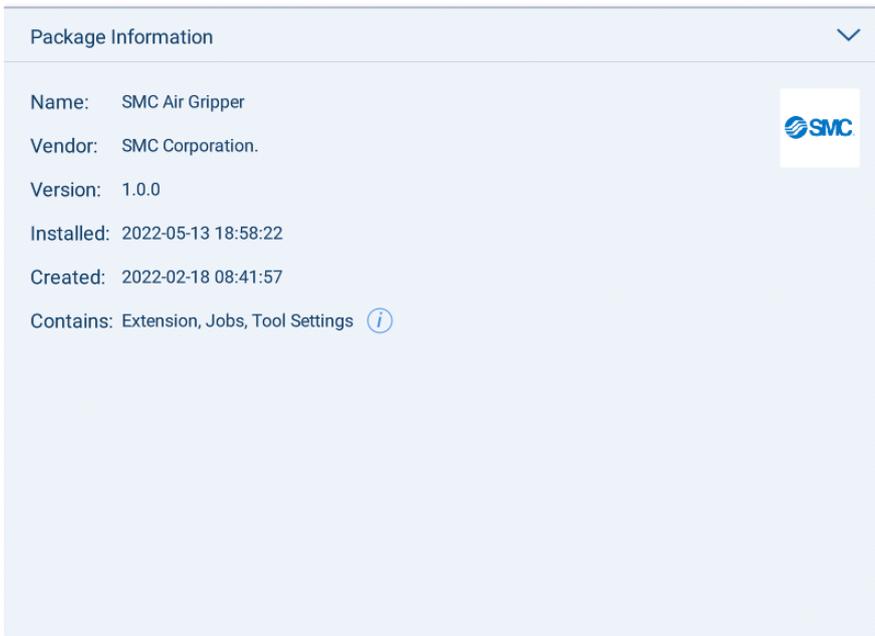
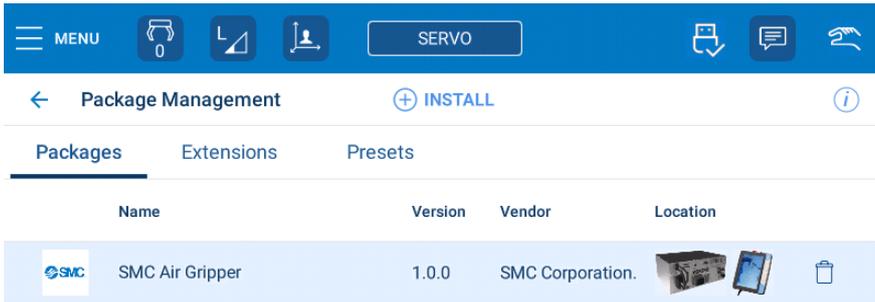


3. Open the “Packages” tab and tap [+INSTALL] at the upper part of the screen. A pop-up dialog box showing the installable packages will appear. From the package list, select “SMC Air Gripper” and install it.
Normally, when the installation has completed, the packages, extension, and tool presets are added to the appropriate list.



4. On the package administration screen, confirm that the installation has completed.

(1) Tap the “Packages” tab, and confirm that SMC Air Gripper is added to the list.



(2) Tap the “Extensions” tab, and confirm that the SMC Air Gripper is added to the list.

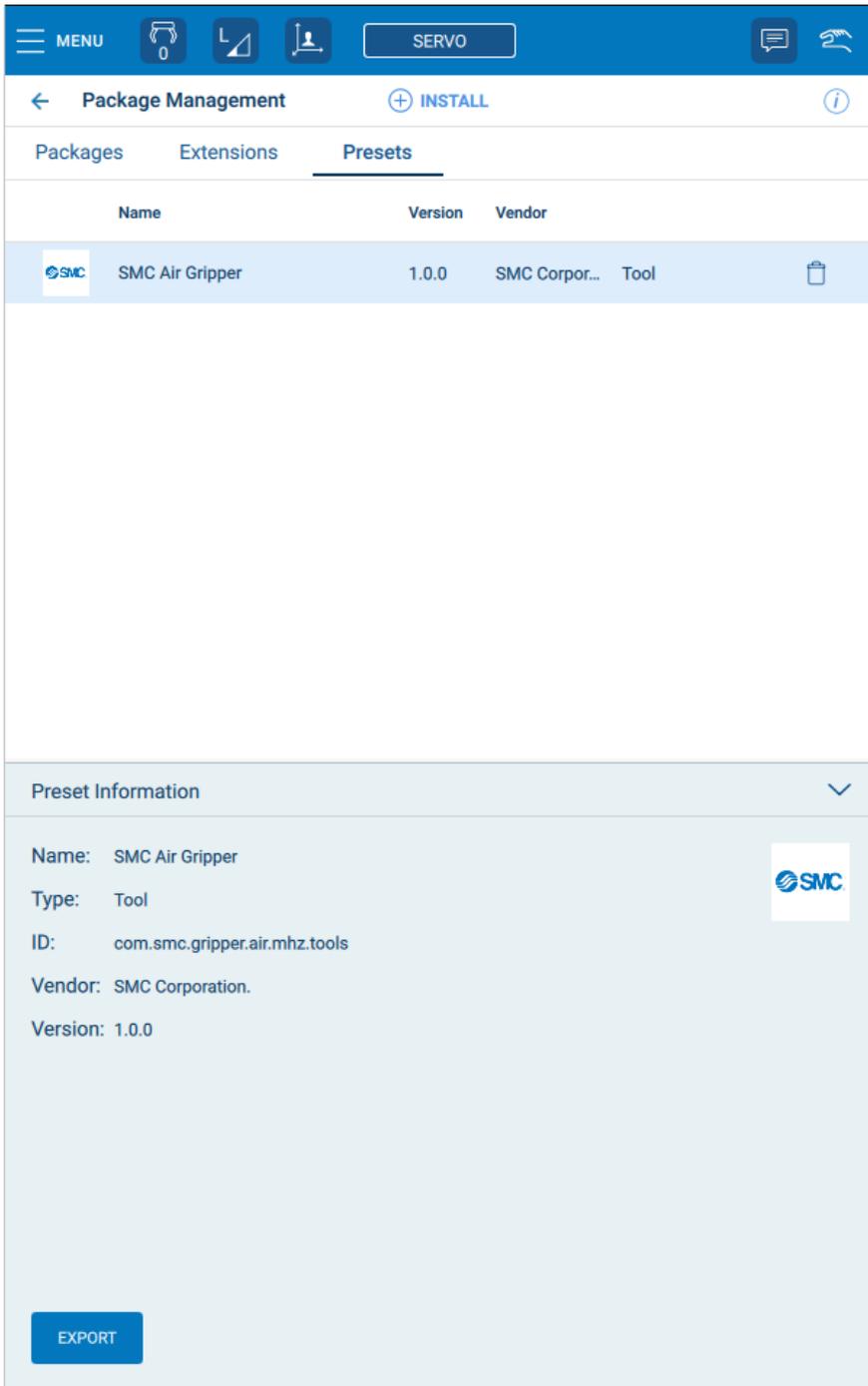
The screenshot displays the 'Package Management' application interface. At the top, there is a blue header bar with a 'MENU' icon, a 'SERVO' button, and a '0' indicator. Below the header, the 'Package Management' title is shown with a back arrow and an 'INSTALL' button. The 'Extensions' tab is selected, showing a table with the following data:

Name	Version	Vendor	Status
 SMC Air Gripper Extension	1.0.0	SMC Corporation.	<input type="radio"/>

Below the table, there is an 'Extension Information' section with a dropdown arrow. The information displayed is:

- Name: SMC Air Gripper Extension
- Vendor: SMC Corporation. 
- Version: 1.0.0
- Status: Inactive
- Enabled:

(3) Tap the “Presets” tab, and confirm that SMC Air Gripper is added to the list.



5-4-2. Tool Presets

When you select 'SMC Air Gripper' from the drop-down list of installed tool presets, the settings of the tool properties of the SMC Air Gripper are immediately copied to the text fields of appropriate tool settings of the currently selected tool. As the properties cannot be immediately applied, they can be further manually edited before they are saved.

Tool #5: CTool5 Select preset to apply: SMC Air Gripper

General Interference

Name: CTool5 Block I/O: Not Assigned

Tool Center Point (TCP) Orientation: ESTIMATE Show without tool

X _F	0.000 mm	R _x	0.0000 deg
Y _F	0.000 mm	R _y	0.0000 deg
Z _F	0.000 mm	R _z	0.0000 deg

Weight: ESTIMATE

W	0.000 kg	Center of Gravity (X _G , Y _G , Z _G)	
X _G	0.000 mm	I _x	0.000 kg·m ²
Y _G	0.000 mm	I _y	0.000 kg·m ²
Z _G	0.000 mm	I _z	0.000 kg·m ²

Tool #5: SMC Air Gripper PRESETS

General Interference

Name: SMC Air Gripper Block I/O: Not Assigned

Tool Center Point (TCP) Orientation: ESTIMATE Show without tool

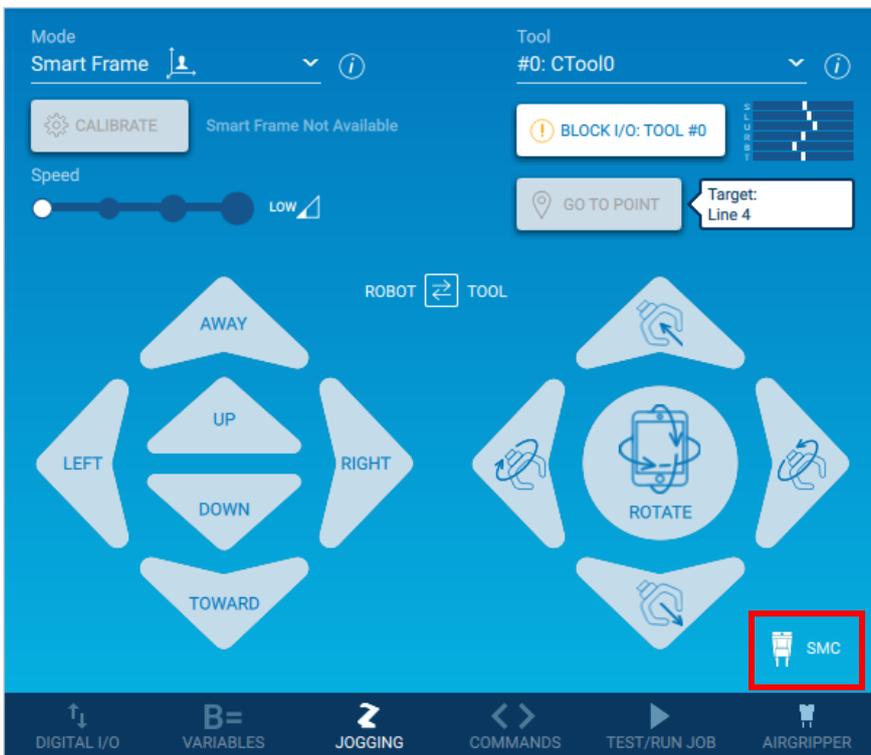
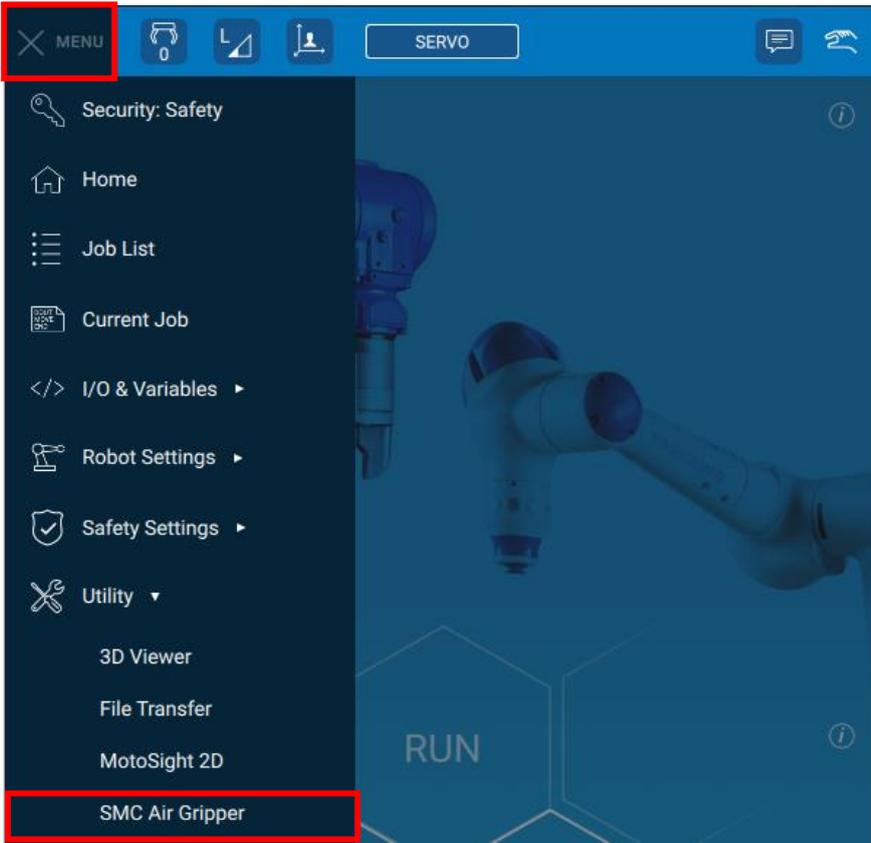
X _F	0.000 mm	R _x	0.0000 deg
Y _F	0.000 mm	R _y	0.0000 deg
Z _F	135.000 mm	R _z	0.0000 deg

Weight: ESTIMATE

W	0.440 kg	Center of Gravity (X _G , Y _G , Z _G)	
X _G	2.400 mm	I _x	0.001 kg·m ²
Y _G	0.000 mm	I _y	0.001 kg·m ²
Z _G	42.600 mm	I _z	0.000 kg·m ²

5-4-3. Utility Window

1. Select [MENU] at the upper left of the screen, tap [Utility] -> [SMC Air Gripper], or tap [JOGGING] on the job contents review screen and then tap the “Air gripper” icon at the lower right of the screen to open the utility window.



2. Utility Window Features

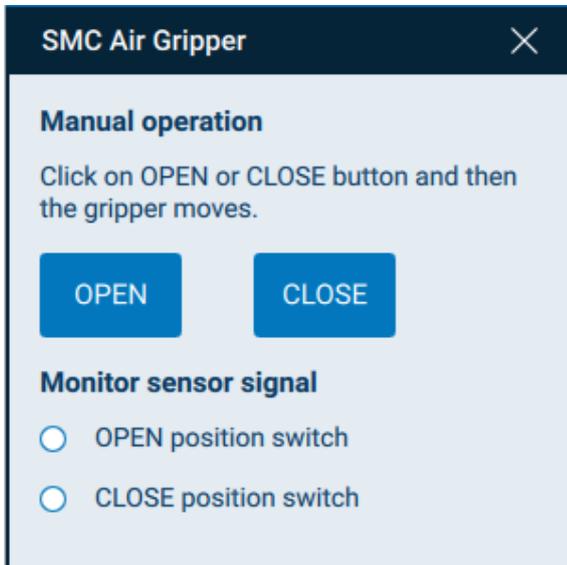
(1) Manual operation

It is possible to check the manual operation of the Air Gripper.

By tapping the OPEN or CLOSE button, it is possible to perform an opening or closing action of the gripper.

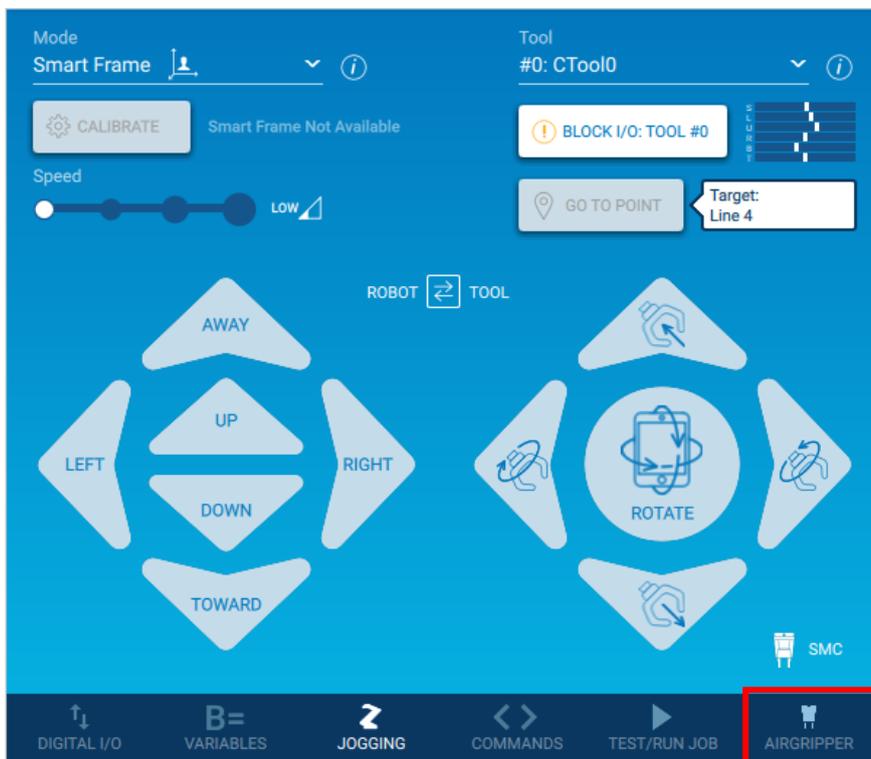
(2) Monitor sensor Signal

It is possible to confirm whether the Open or Close position auto switches react.



5-4-4. Air Gripper Integration Window

1. On the Job Contents review screen, tapping [AIRGRIPPER] on the navigation bar opens the "Air Gripper" Integration Window.



2. Insert Commands Tab

(1) Selection Operation

Select the behaviour of the Open or Close operations.

•OPEN ONLY

Puts the gripper into the “Open state”, recognises it as “Open success” without checking the Open position signal, and proceeds to the next operation.

•OPEN AND CHECK SIGNAL

Puts the gripper into the “Open state” and waits for the Open position signal input before proceeding to the next operation. When the signal is turned on, the software recognises it as “Open success” and proceeds to the next operation.

•CLOSE

Puts the gripper into the “Closed state”, recognises it as “Close success” without checking the Close position signal, and proceeds to the next operation.

•CLOSE AND CHECK SIGNAL

Puts the gripper into the “Closed state” and waits for the Close position signal input before proceeding to the next operation. When the signal is turned on, the software recognises it as “Close success” and proceeds to the next operation.

(2) INSERT COMMAND

It is possible to add commands for controlling the gripper opening/closing action to the job.

•SMC_OPEN_AIRGRIPPER

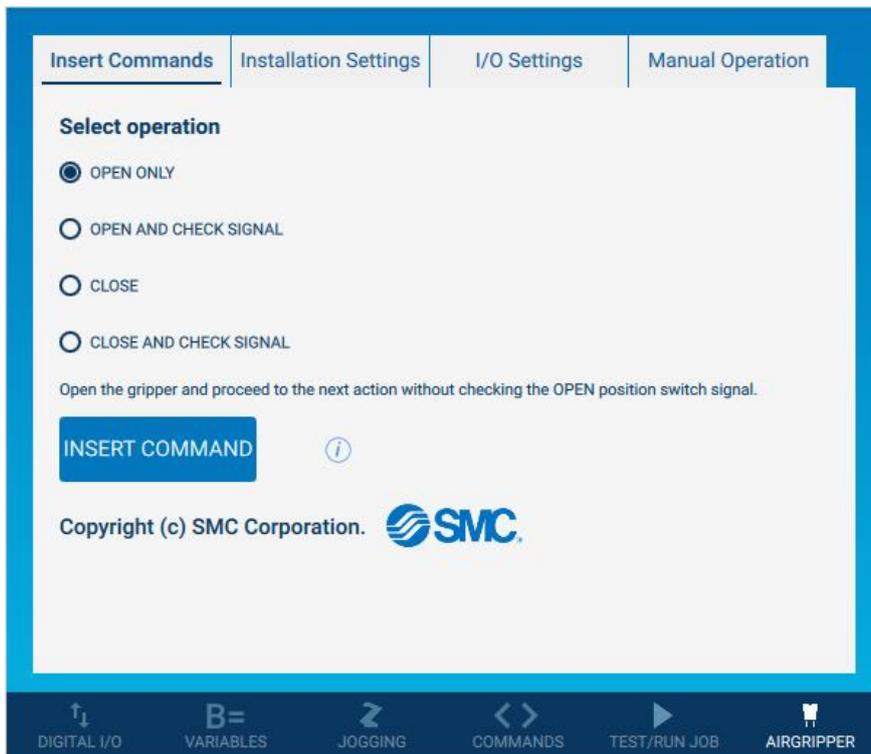
This command is used to make a gripper opening action.

If you select “OPEN ONLY” or “OPEN AND CHECK SIGNAL” this command will be added.

•SMC_CLOSE_AIRGRIPPER

This command is used to make a gripper closing action.

If you select “CLOSE ONLY” or “CLOSE AND CHECK SIGNAL” this command will be added.



3. Installation Settings Tab

* To change the setting, set the security access level to the administration level.

(1) Select a valve option.

Check the product number, and then select a valve option that suits the type of the air gripper you are using.

Nil: no symbol

N.O. : Normally open

N.C. : Normally closed

(2) Gripper operation completion waiting time

This is the set value for the waiting time after the valve is operated for the finger opening/closing action to turn on.

Adjust the opening of the exhaust restrictor and enter an appropriate value according to the gripper finger opening/closing operation time. The default value is 500ms. It can be set in the range of 0 to 1000ms.

(3) Status signal output to digital output port.

Select whether to output a status signal to the digital output port when "Open/Close success" or "Open/Close failure" is detected.

When "Enabled" is selected:

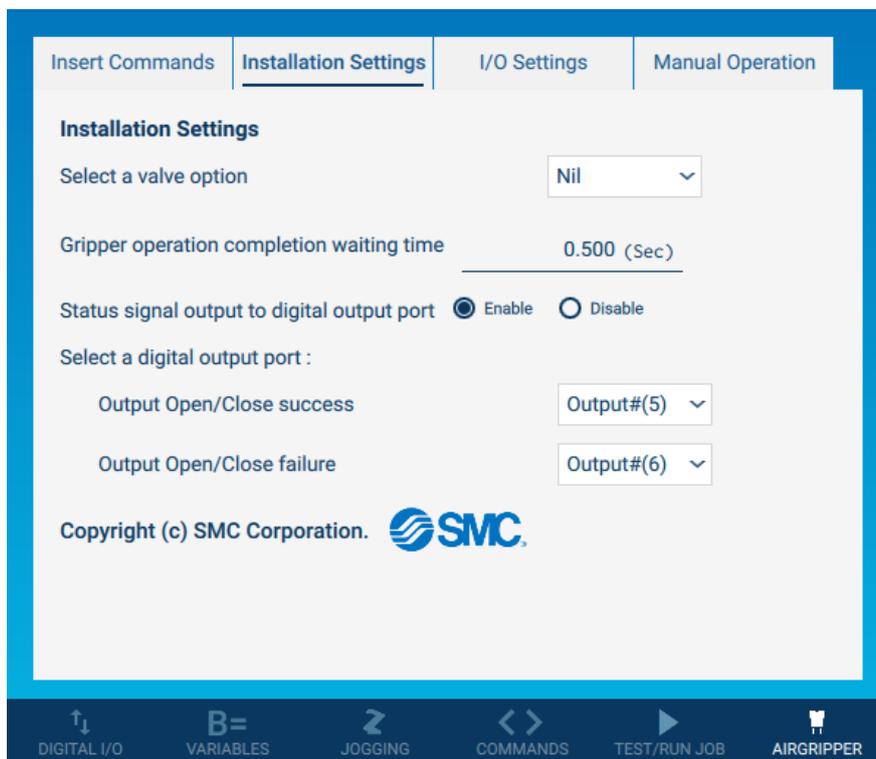
Selection of the digital output port is enabled. If either of "Open/Close success" and "Open/Close failure" is detected, the corresponding digital output port is turned on.

When "Disabled" is selected:

The selection of the digital output port is disabled. Even if either of "Open/Close success" and "Open/Close failure" is detected, no status signal is output.

(4) Select a digital output port

Selected box operation is enabled when "Output status signal to digital output port" is enabled. Select the digital output port to which a status signal is output when "Open/Close success" or "Open/Close failure" is detected.



4.I/O Settings Tab

* To change the setting, set the security access level to the administration level.

(1) I/O settings for gripper operation

At the time of installation of the YASKAWA Plug & Play Kit, the I/O assignment is already set. If wiring is made as per the manual, it can be used with the default setting.

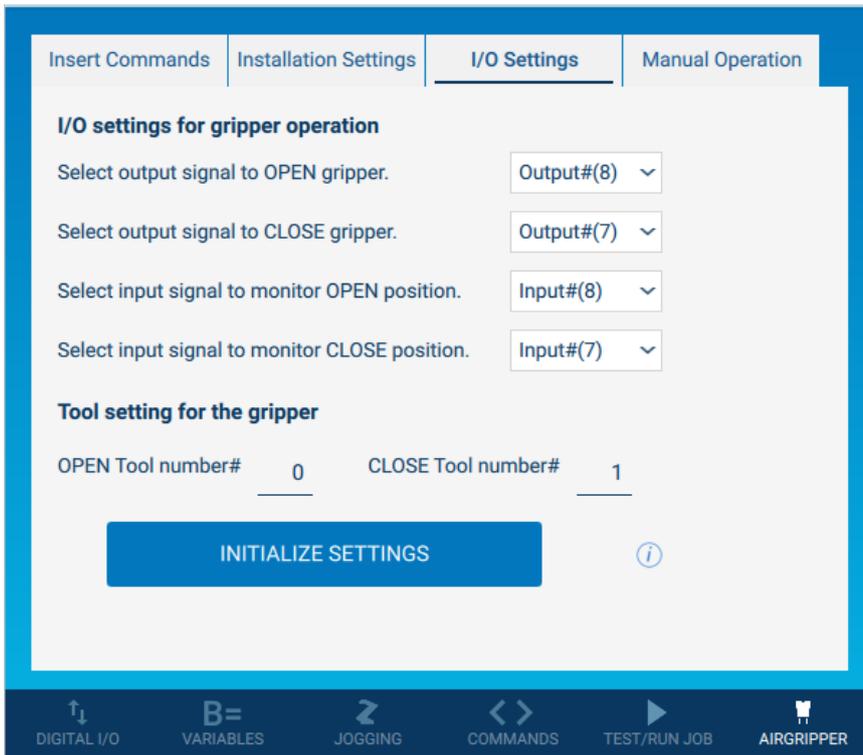
However, if the wiring is changed to connect with another device, it is possible to change the signal setting for gripper operation from this tab.

If you intend to return the I/O setting to the factory default condition, pressing the button at the lower part of the screen can initialize this setting.

(2) Tool setting for the gripper

The collaborative robot calculates the external force by canceling the tool mass. For this purpose, it is necessary to set the tool to be mounted on the manipulator and the masses and the centers of gravity of the tool and workpiece should be set in the tool file.

In the initial setting, the tool number 0 is selected when the OPEN button is pressed. Tool number 1 is selected when the CLOSE button is pressed. The tool number can be changed.



5. Manual Operation tab

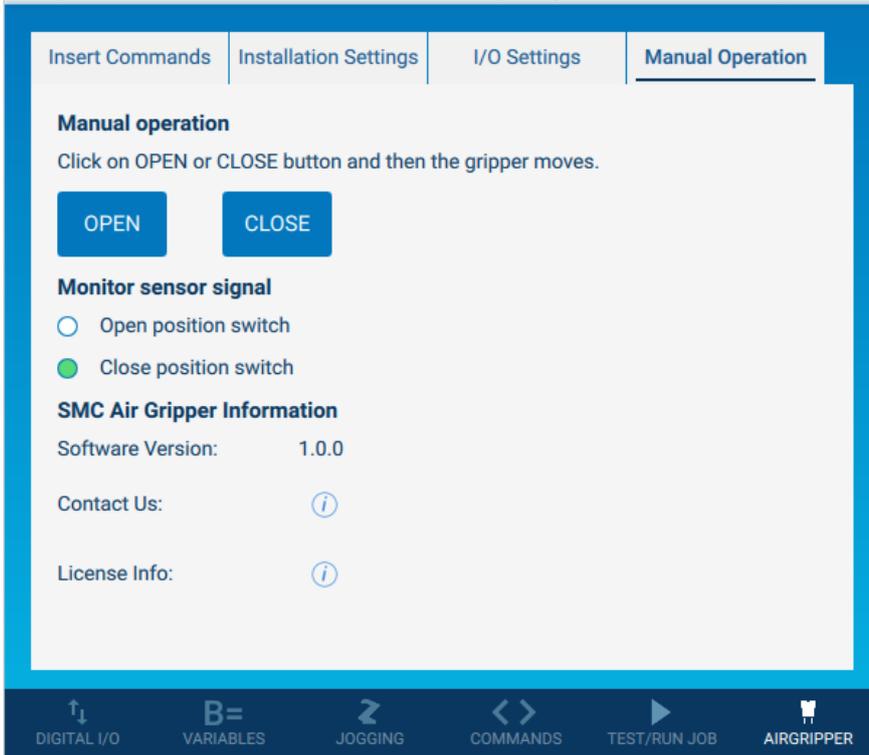
(1) Manual operation

The manual operation of the air gripper can be checked.

By tapping the OPEN or CLOSE button, it is possible to perform an opening or closing action of the gripper.

(2) Monitor sensor signal

It is possible to confirm whether the Open position or Close position auto switch reacts.



5-5. Air supply

Warning

1. Please contact SMC when using the product in applications other than with compressed air.
2. Compressed air containing a large amount of drainage can cause the malfunction of pneumatic equipment. An air dryer or water separator should be installed upstream from filters.
3. If condensation in the drain bowl is not emptied on a regular basis, the bowl will overflow and allow the condensation to enter the compressed air lines. This causes the malfunction of pneumatic equipment. If the drain bowl is difficult to check and remove, the installation of a drain bowl with an auto drain option is recommended.
- 4) Use clean air.
Do not use compressed air that contains chemicals, synthetic oils including organic solvents, salt or corrosive gases, etc., as it can cause damage or malfunction of equipment.
For detailed information regarding the quality of the compressed air described above, refer to SMC's "Air Cleaning Systems".

Caution

1. When dry air is used as the fluid, degradation of the lubrication properties inside the equipment may occur, resulting in reduced reliability (or reduced service life) of the equipment. Please consult with SMC.
2. Install air filters.
Install an air filter at the upstream side of valve. Select an air filter with a filtration degree of 5µm or finer.
3. Install an aftercooler, air dryer or drain catch before the filter and take appropriate measures.
Compressed air that contains excessive foreign material may cause malfunction of valves and other pneumatic equipment.
Therefore, take appropriate measures to ensure air quality, such as by providing an aftercooler, air dryer or water separator.

4. Use the product within the specified fluid and ambient temperature range.

If the fluid temperature is 5°C or Cable at the bottom, the moisture in the circuit could freeze, causing damage to the seals and leading to equipment malfunction. Therefore, take appropriate measures to prevent freezing.

For detailed information regarding the quality of the compressed air described above, refer to SMC's "Air Cleaning Systems".

5-6. Piping

Caution

1. Refer to the Fittings and Tubing Precautions (Best Pneumatics) for handling one touch fittings.
2. Before piping
Before piping, blow air (flush) or clean the piping to remove any cutting chips, cutting oil, dust, etc.

5-7. Operating environment

Warning

- 1) Do not use in an atmosphere where corrosive gases, chemicals, sea water, water or water steam is present.
2. Do not expose the product to direct sunlight for an extended period of time.
3. **Do not operate in a location subject to vibration or impact.**
4. Do not mount the product in locations where it is exposed to radiant heat.
5. Do not use this product in an area that is dusty, or in an environment in which water or oil splashes on to the cylinder.

Caution

1. Martensitic stainless steel is used for the finger guide rail, so make sure that anti-corrosiveness is inferior to the austenitic stainless steel. Especially rust may be generated in environments that allow water drops from condensation to stay on the surface.

5-8. Lubrication

Caution

1. The non-lube type air gripper is lubricated at the factory, and can be used without any further lubrication.
If a lubricant is used in the system, use turbine oil Class 1 (with no additive) ISO VG32.
Furthermore, once lubrication is applied, it must be continued.
If lubrication is later stopped, malfunction can occur due to loss of the original lubricant.
Refer to the Material Safety Data Sheet (MSDS) of the hydraulic fluid when supplying the fluid.

6. Maintenance

Warning

1. If handled improperly, compressed air can be dangerous. The assembly, handling, repair and element replacement of pneumatic systems should be performed by a knowledgeable and experienced person.
2. Remove drainage from air filters regularly.
3. When air grippers are removed, first confirm that measures are in place to prevent any workpieces from dropping, run-away of equipment, etc. Then cut off the supply pressure and electric power and exhaust all compressed air from the system using the residual pressure release function.
When the equipment is restarted, proceed with caution after confirming that appropriate measures are in place to prevent cylinders from sudden movement.
4. Do not allow people to enter or place objects in the carrying path of the air gripper.
Otherwise, injury or an accident may occur.
5. Do not put hands, etc. in between the air gripper fingers or attachments.
Otherwise, injury or an accident may occur.

6. When removing the air gripper, first confirm that no workpieces are being held and then release the compressed air before removing the air gripper.

If a workpiece is still being held, there is a danger of it being dropped.

Revision history
D. YASKAWA Plug & Play Kit add.
E. Wiring examples to robot controllers add.

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Note: Specifications are subject to change without prior notice and any obligation on the part of the manufacturer.
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