

JXC5H/6H series

How to set the parameter version for LEFS#F

JXC5H/6H can be used by writing the actuator mounting posture (horizontal, vertical), transport weight, and parameters for each speed (7 types) in JXC-BCW.

Since the parameter version and operating conditions are described below, set the parameter version that matches the operating conditions in the parameter conditions and write.



Figure 1 Parameter condition input screen

Table 1 Parameter version and operating conditions

Parameter No	Operating conditions			
	Mounting posture	Transport weight	Speed	Acceleration
1.01	Horizontal	Heavy	Low speed	3000mm/s ²
1.02			↓	
1.03			↓	
1.04			High speed	
1.05		Light	Low speed	9800mm/s ²
1.06			High speed	
1.07	Vertical	Common setting		

1.00	Factory default
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For the JXC5H/6H series, parameters can be rewritten with JXC-BCW even with controllers other than the blank controller (JXC5H/6H*-BC).

Write parameters to a controller other than the blank controller (JXC5H/6H*-BC)

When using, write the parameters of the actuator that matches the controller part number.

ex) Controller part number JXC5H71-LEFS25FA-200

